

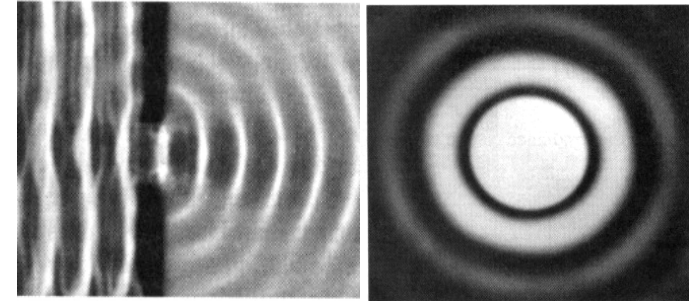
Lenses and Depth of Field

Prepared by Behzad Sajadi

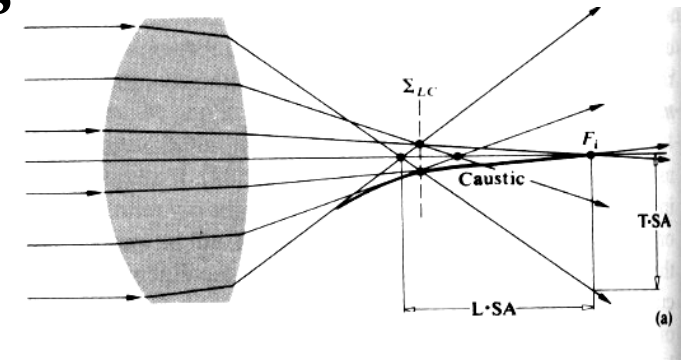
**Borrowed from Frédo Durand's
Lectures at MIT**

3 major type of issues

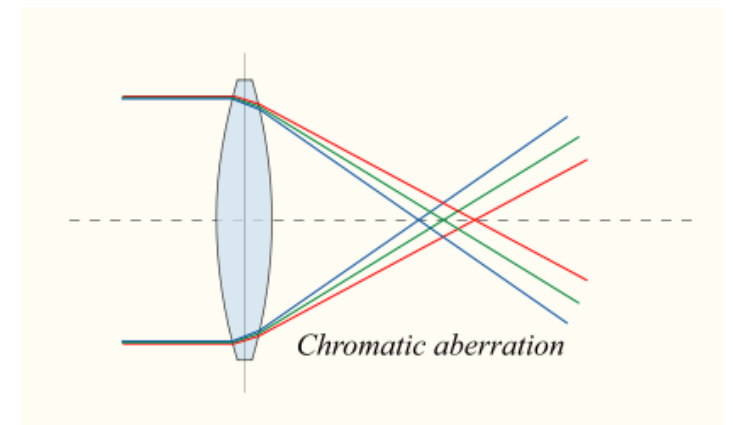
- **Diffraction**
 - ripples when aperture is small



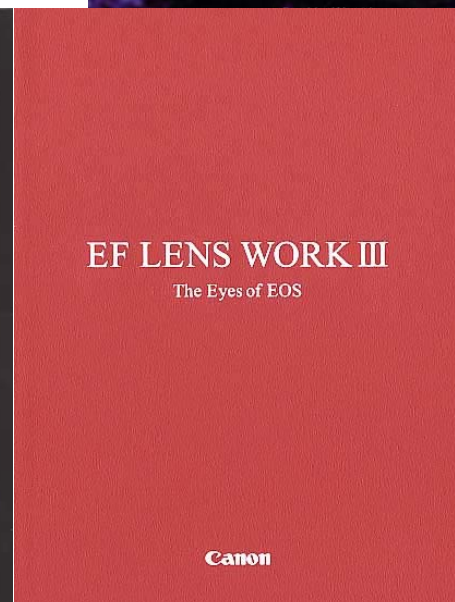
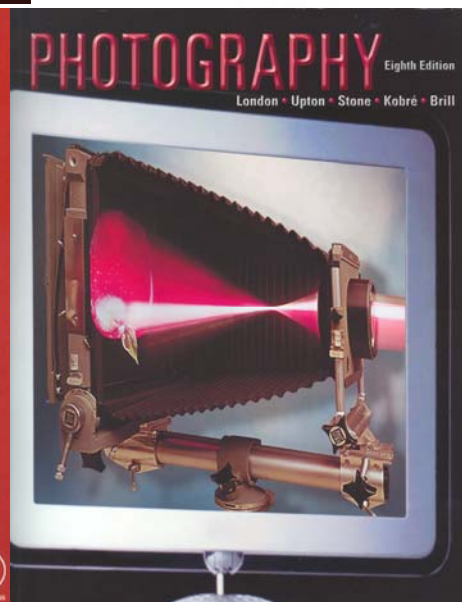
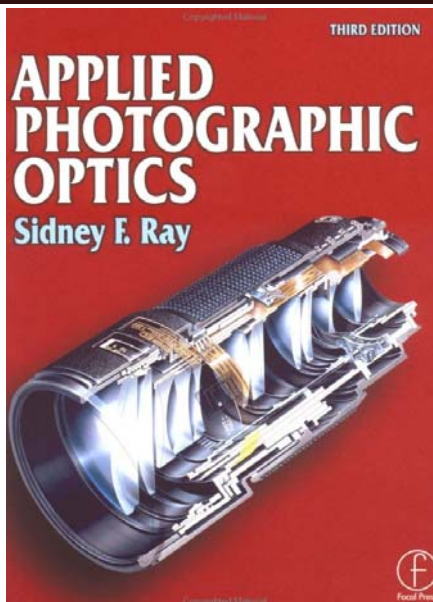
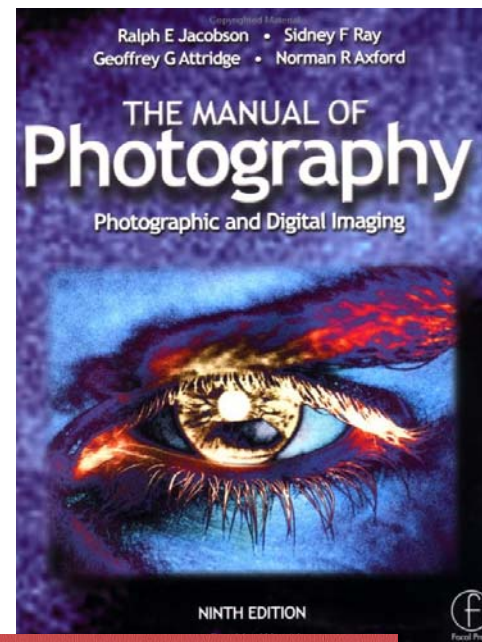
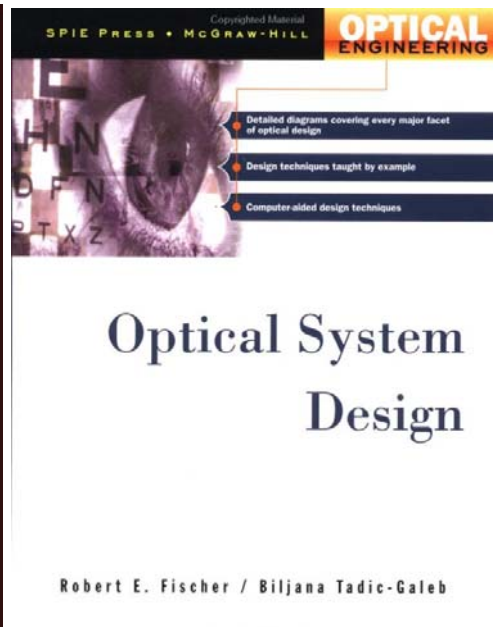
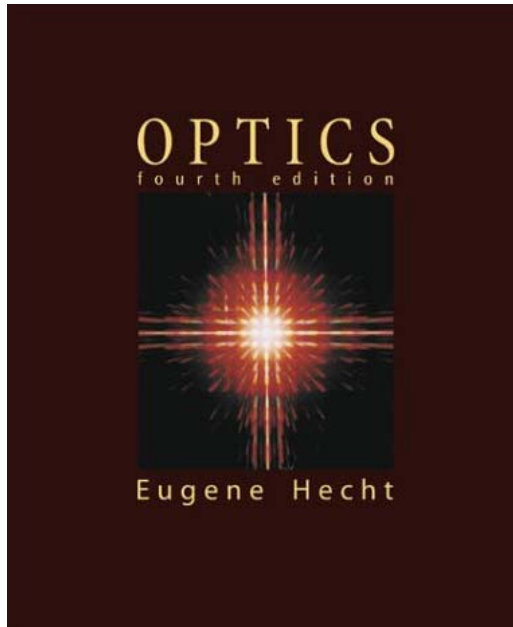
- **Third-order/spherical aberrations**
 - Rays don't focus
 - Also coma, astigmatism, field curvature



- **Chromatic aberration**
 - Focus depends on wavelength



References



Links

- http://en.wikipedia.org/wiki/Chromatic_aberration
- <http://www.dpreview.com/learn/?/key=chromatic+aberration>
- <http://hyperphysics.phy-astr.gsu.edu/hbase/geoopt/aberrcon.html#c1>
- http://en.wikipedia.org/wiki/Spherical_aberration
- [http://en.wikipedia.org/wiki/Lens_\(optics\)](http://en.wikipedia.org/wiki/Lens_(optics))
- http://en.wikipedia.org/wiki/Optical_coating
- <http://www.vanwalree.com/optics.html>
- http://en.wikipedia.org/wiki/Aberration_in_optical_systems
- <http://www.imatest.com/docs/iqf.html>
- <http://www.luminous-landscape.com/tutorials/understanding-series/understanding-mtf.shtml>



Other quality issues

Flare

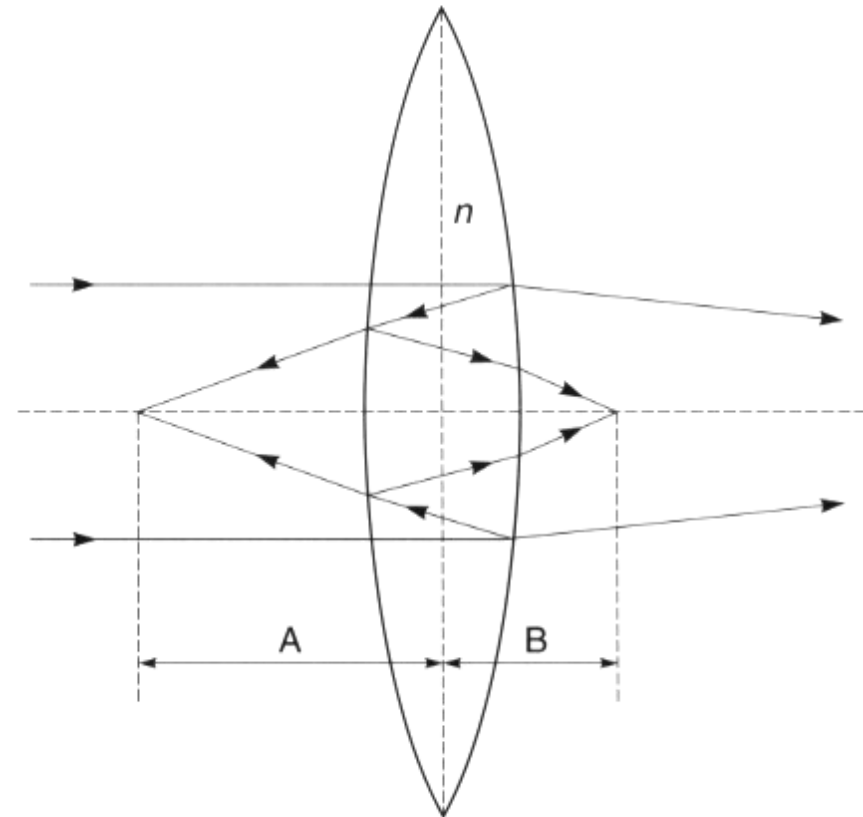


Figure 5.6 Formation of flare spots by a simple lens. Images of the source are formed at distances A and B , where:

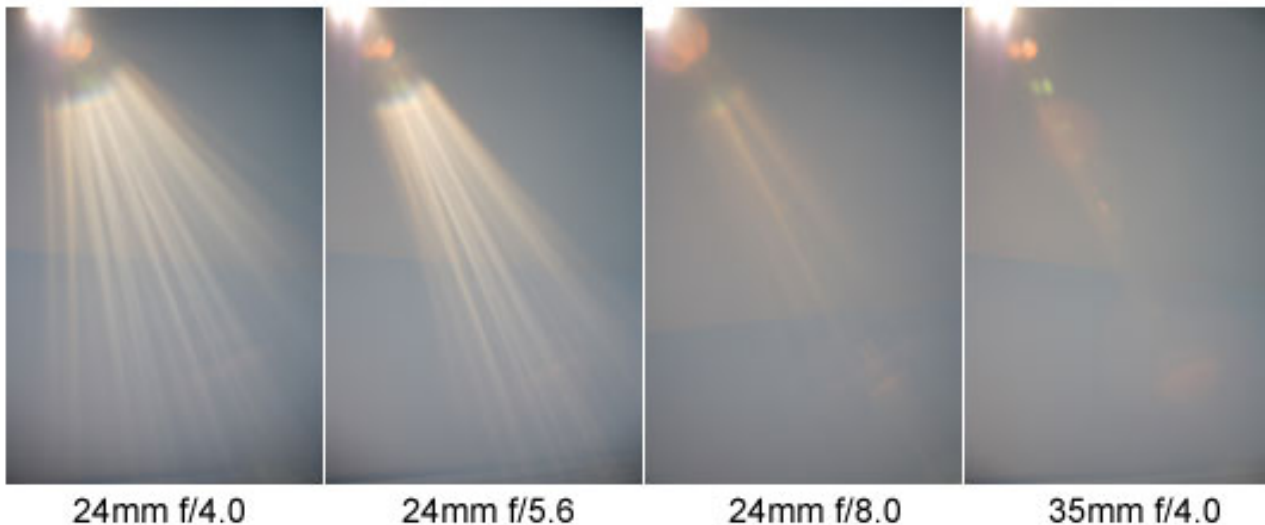
$$A = \left(\frac{n-1}{an-1} \right) f \quad B = \left(\frac{n-1}{bn-1} \right) f$$

and $a = 2, 4, 6 \dots$, $b = 3, 5, 7, \dots$ For $n = 1.5$, $A = f/4, f/10, f/16$ etc. and $B = f/7, f/13, f/19$ etc.

Example of flare "bug"

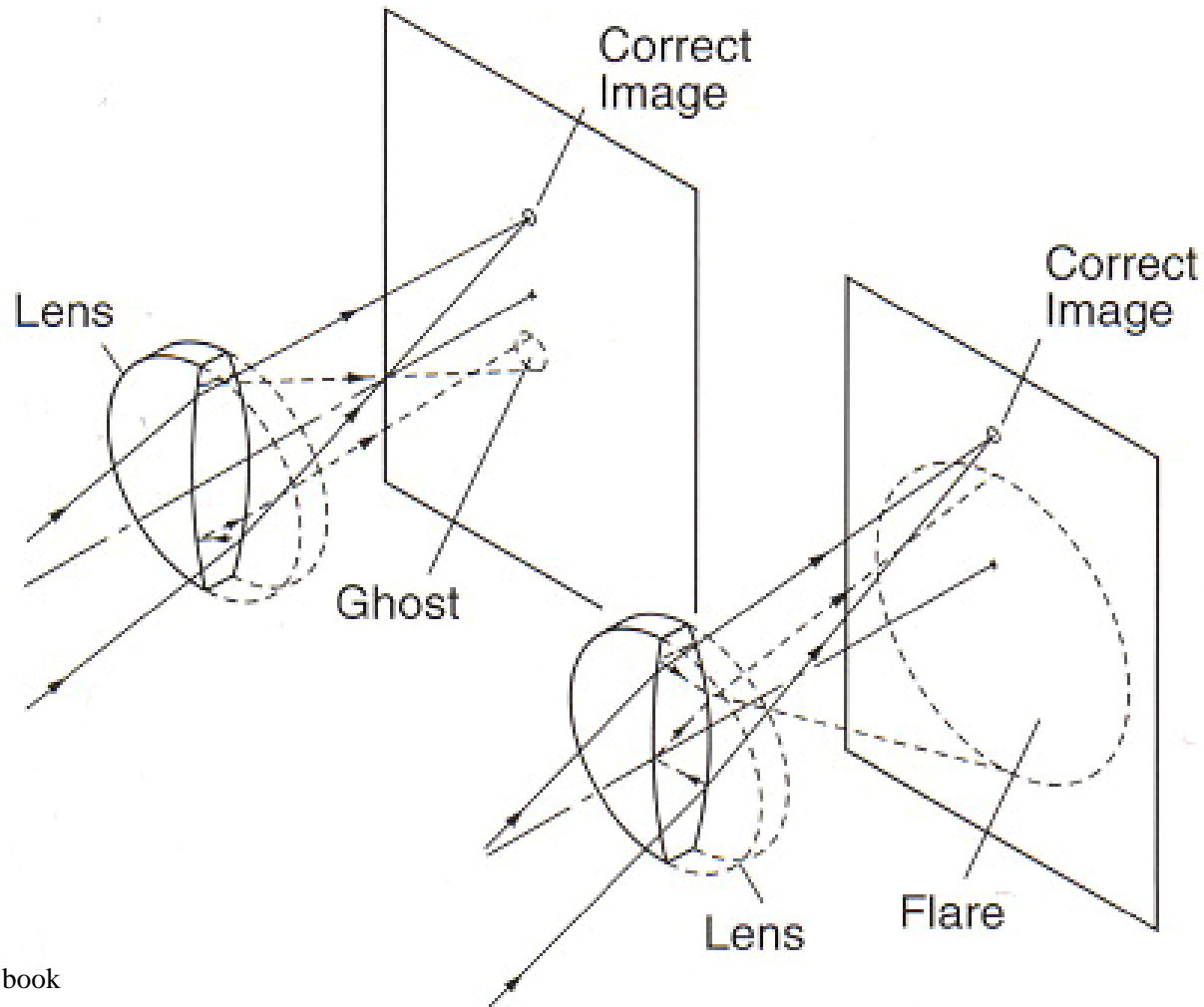
- Some of the first copies of the Canon 24-105 L had big flare problems
- <http://www.the-digital-picture.com/Reviews/Canon-EF-24-105mm-f-4-L-IS-USM-Lens-Review.aspx>
-

Canon 24-105mm f/4 L IS USM Lens Original Flare Problem



Flare and Ghosting

Figure-29 Flare and Ghosting



source: canon red book

Flare/ghosting special to digital

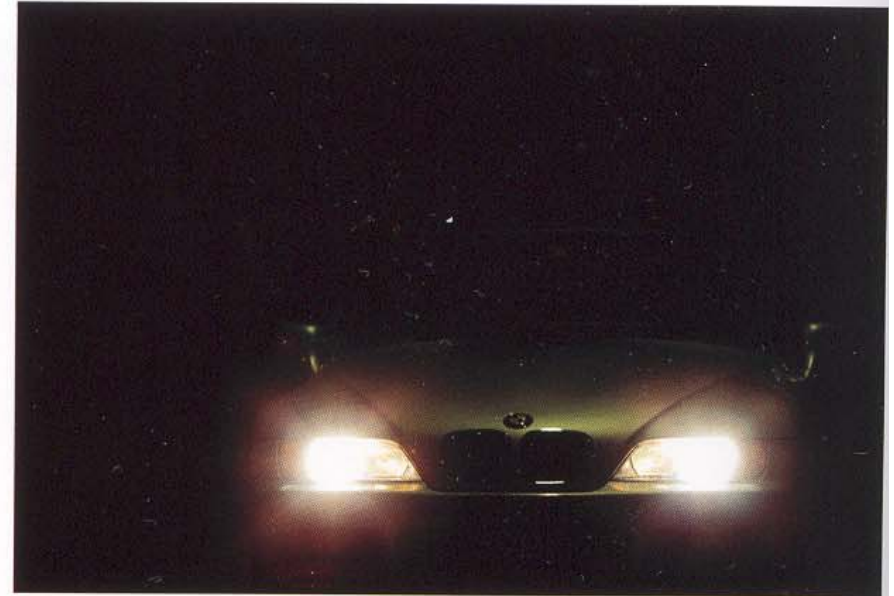


For flat protective glass

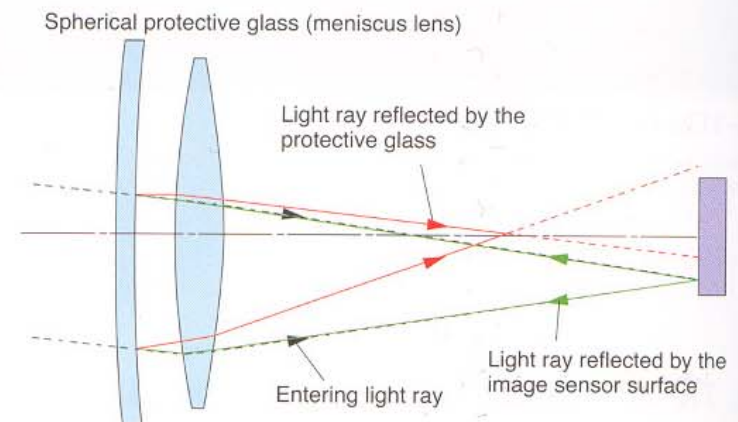
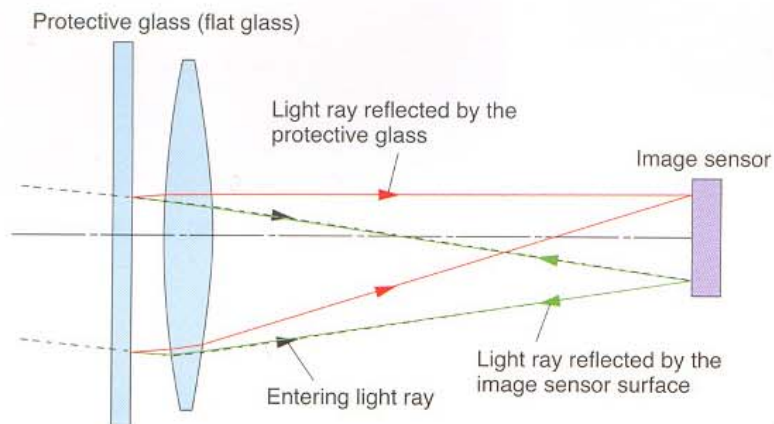


In lenses employing flat protective glass, a reflection occurs between the image sensor and the protective glass, which causes the subject to be photographed in a position different from the actual position.

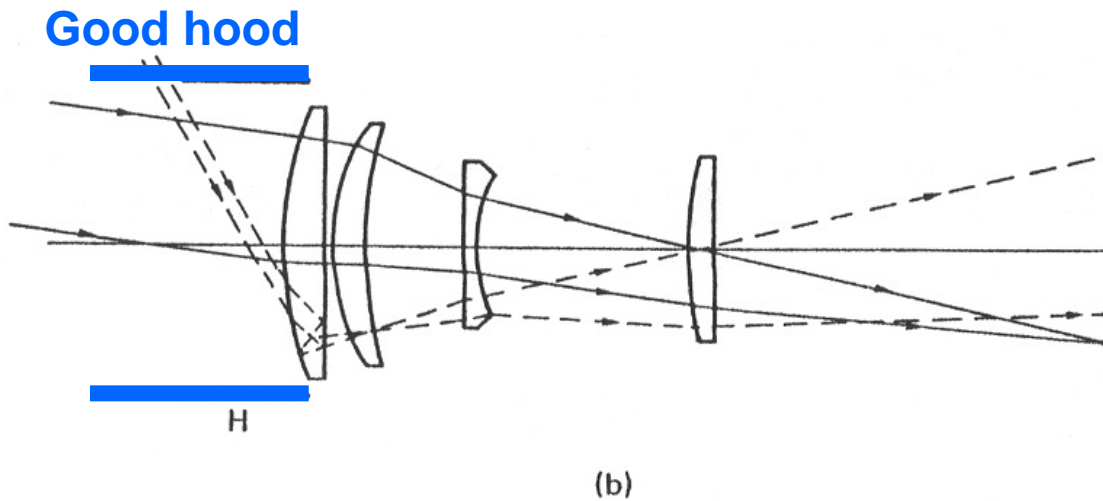
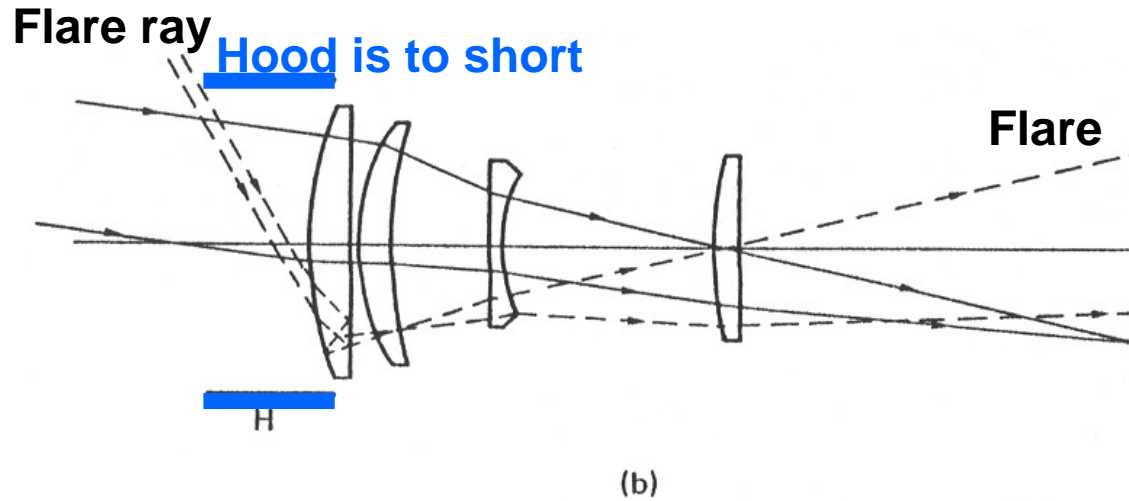
For a meniscus lens



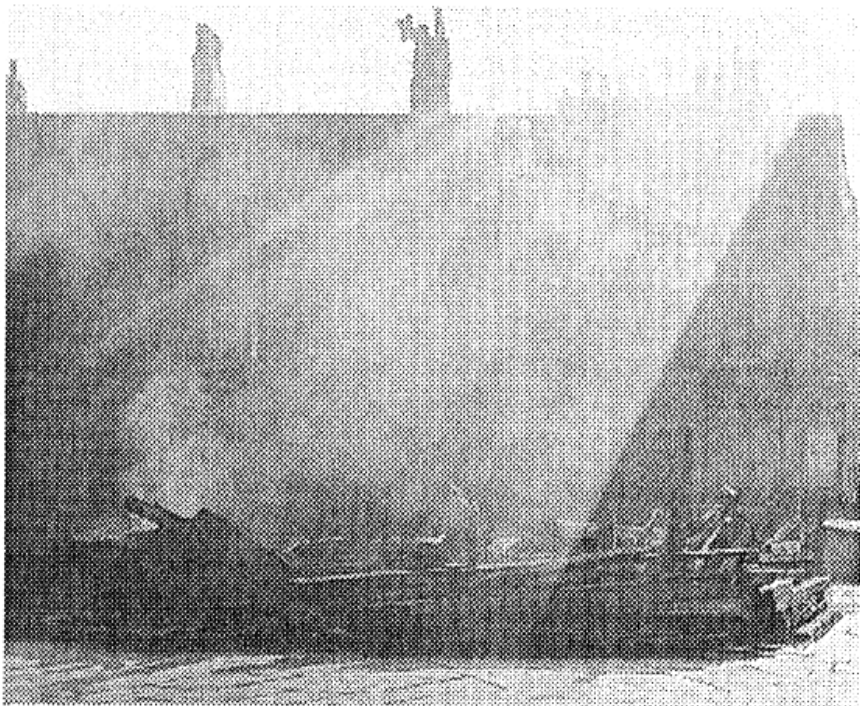
In lenses employing a meniscus lens, no reflection like that seen to the left occurs.



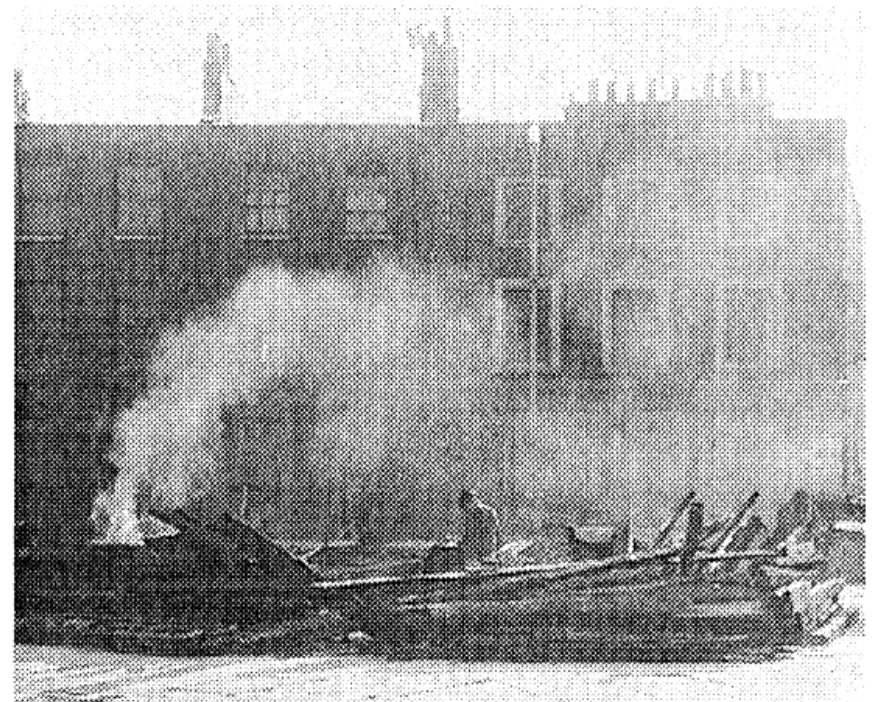
Use a hood! (and a good one)



Lens hood



(a)



(b)

Plate 15.1 Lens flare with an uncoated lens

(a) Flare effects. (b) Reduction of flare by use of a lens-hood.

From Ray's Applied Photographic Optics

Coating

- Use destructive interferences
- Optimized for one wavelength

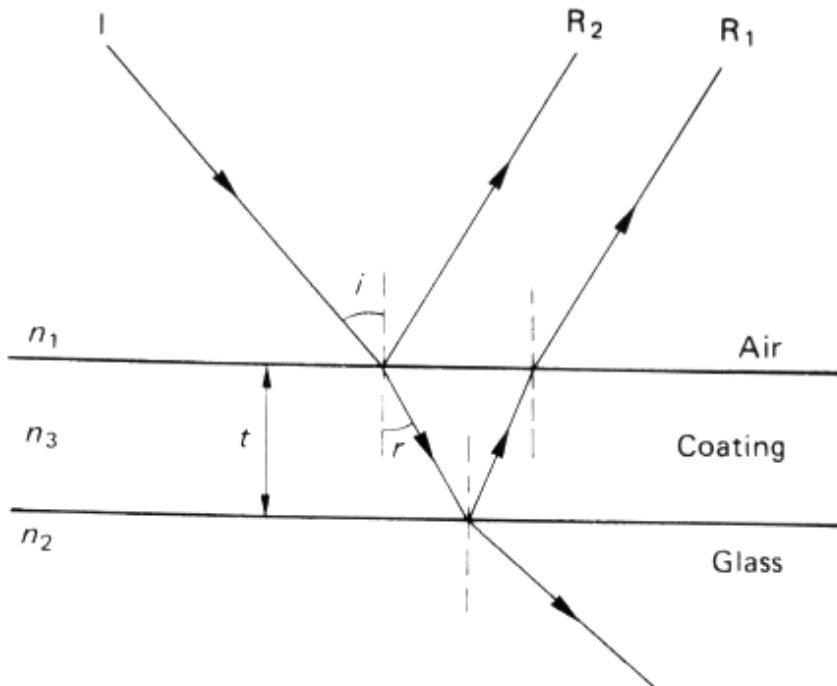


Figure 5.7 An anti-reflection coating on glass using the principle of destructive interference of light between reflections R_1 and R_2

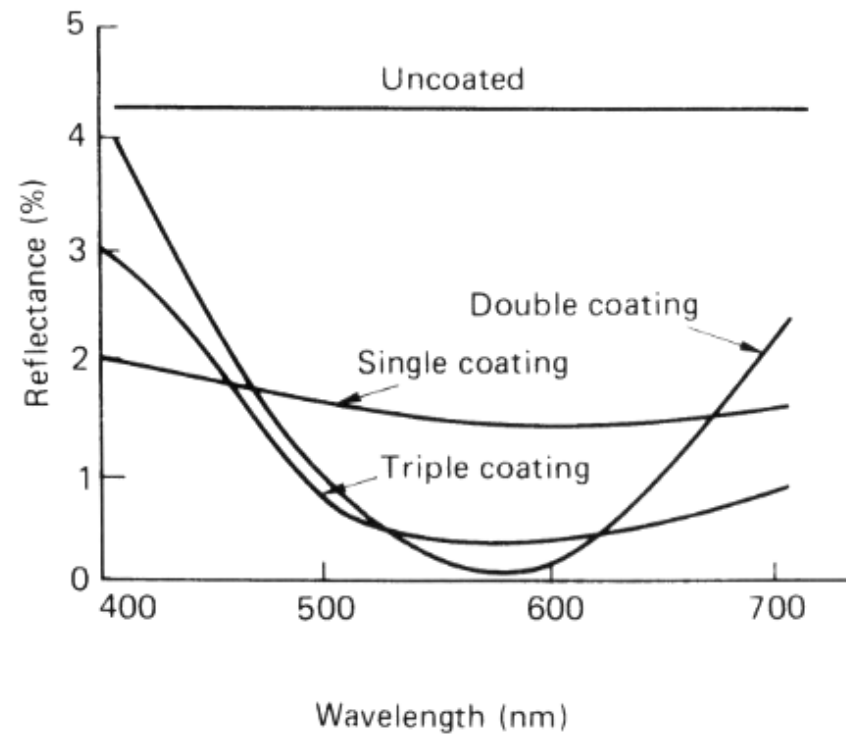
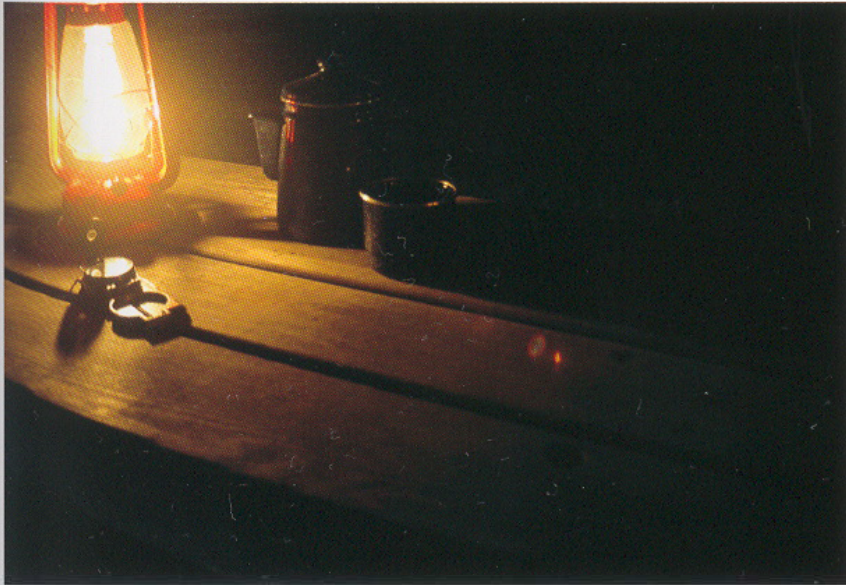


Figure 5.8 The effects on surface reflection of various types of anti-reflection coatings as compared with uncoated glass (for a single lens surface at normal incidence)

Coating for digital

Lens for which the lens shape and coating have not been optimized

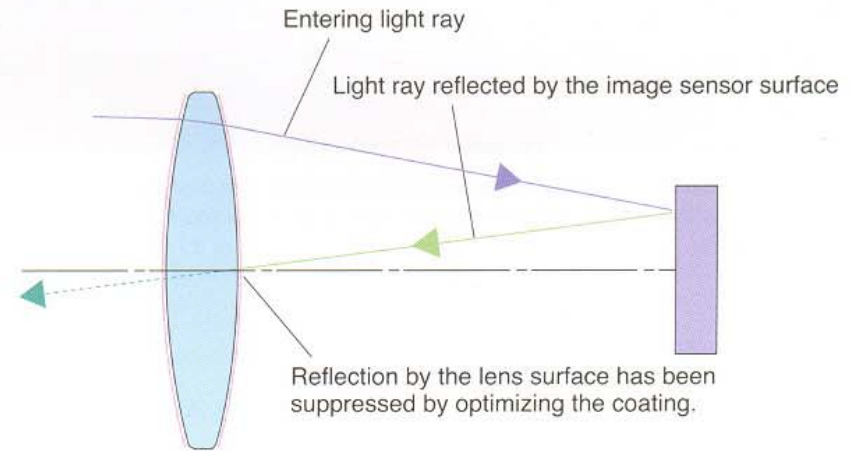
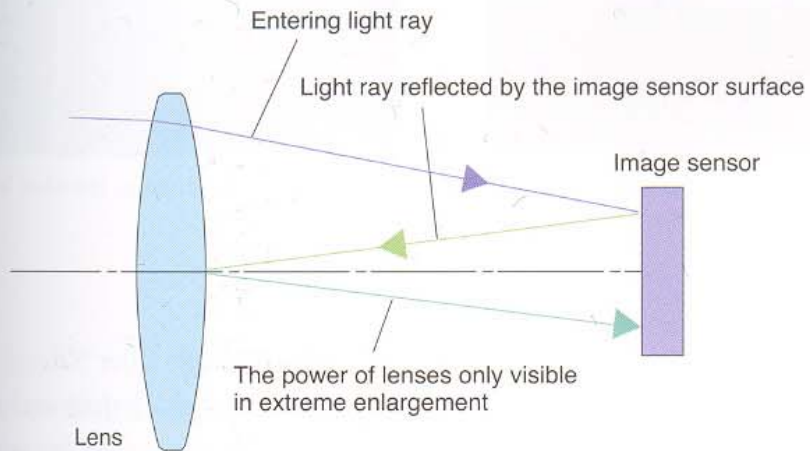


Flaring and ghosting occurs with lens for which the lens shape and coating have not been optimized.

Lens for which the lens shape and coating have been optimized



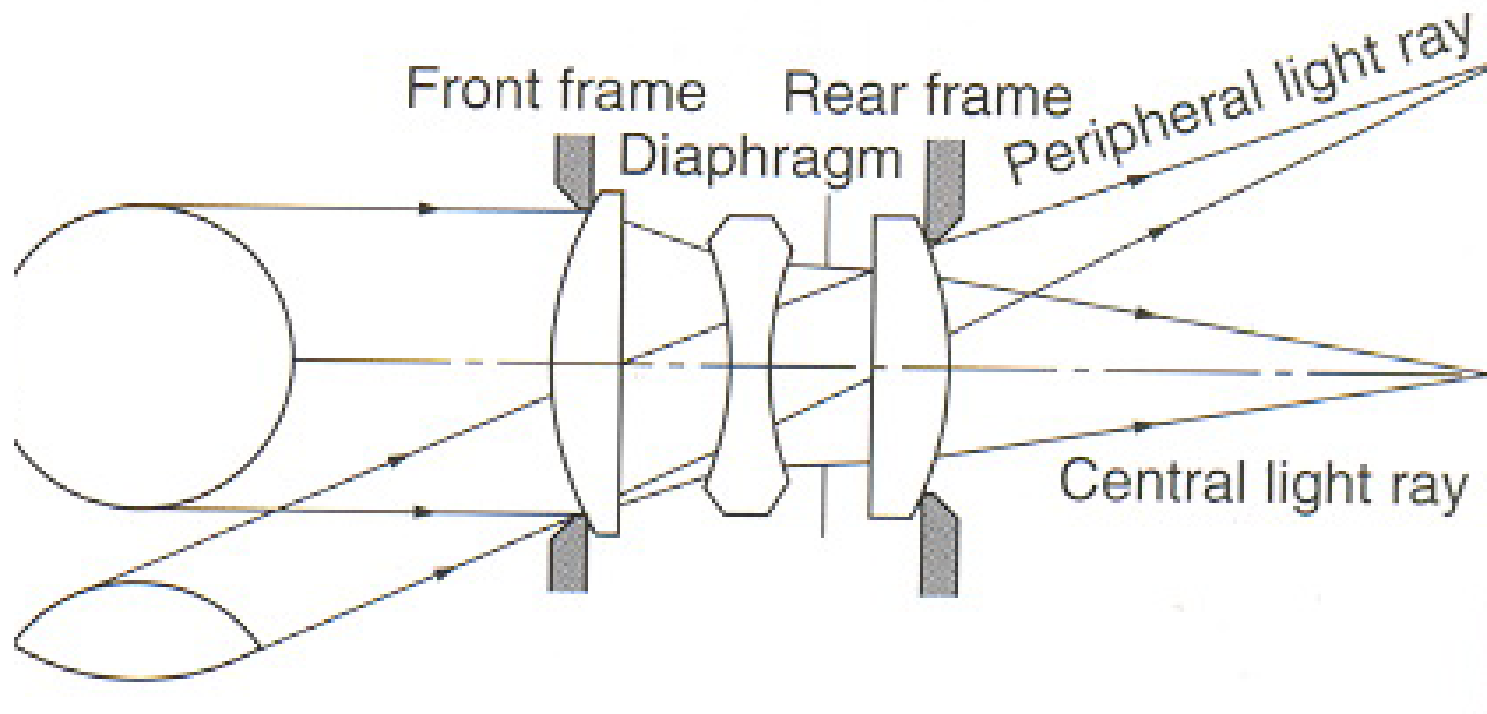
Flaring and ghosting are suppressed with lens for which the lens shape and coating have been optimized.



Vignetting

- The periphery does not get as much light

Figure-28 Vignetting



Vignetting

- <http://www.photozone.de/3Technology/lenstec3.htm>

vignetting



no vignetting





Lens design



Optimization software

- Has revolutionized lens design
- E.g. zooms are good now

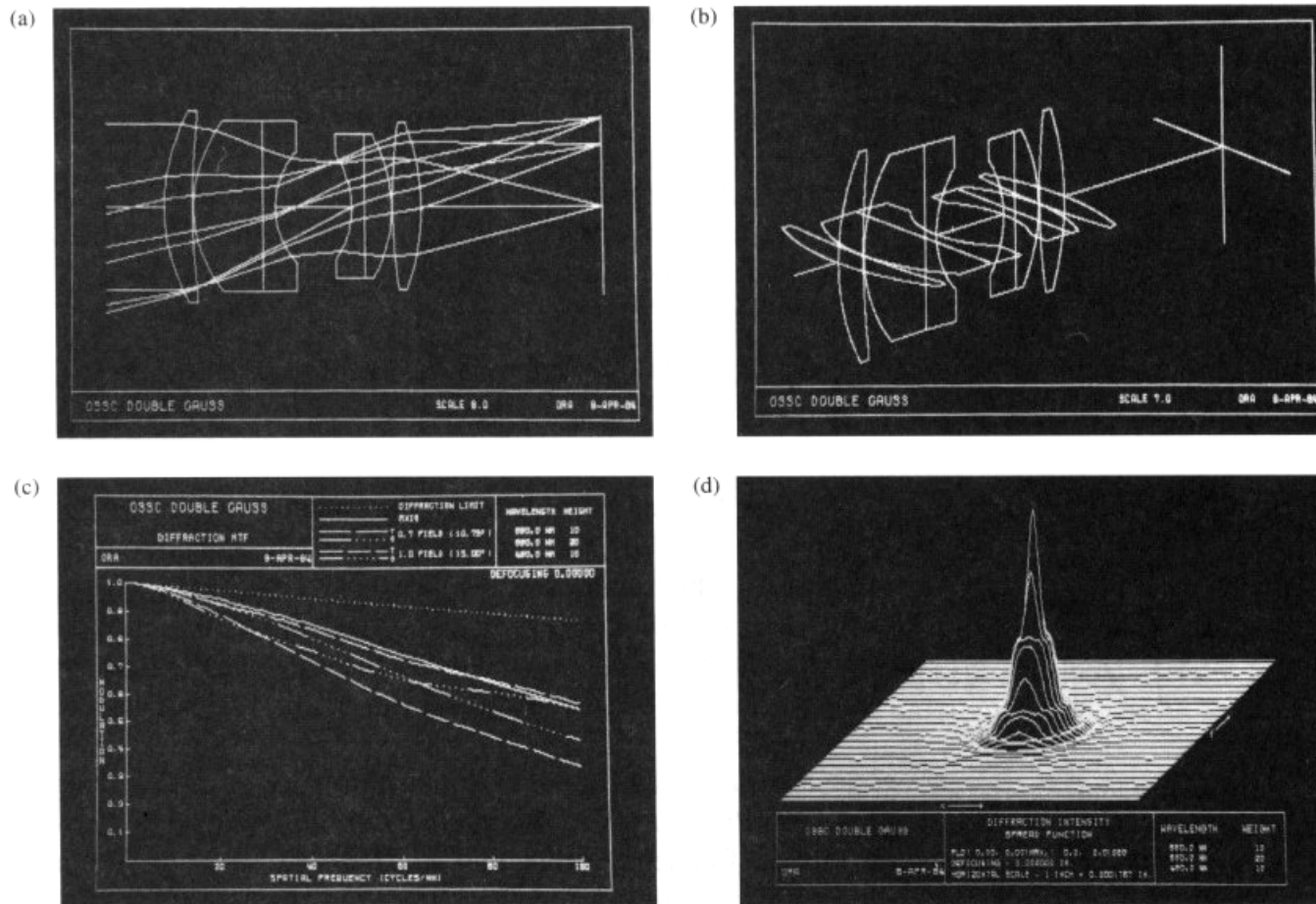


Figure 11.50 An example of the kind of lens design information available via computer techniques. (Photos courtesy Optical Research Associates.)

Lens design, ray tracing

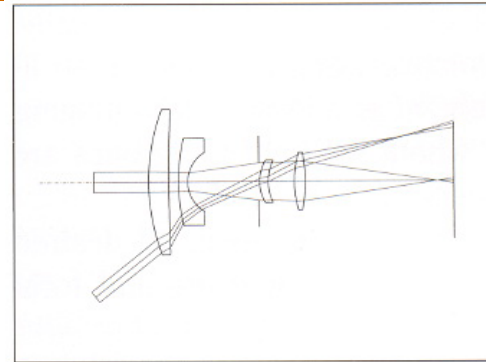


Figure-5

Spot diagram

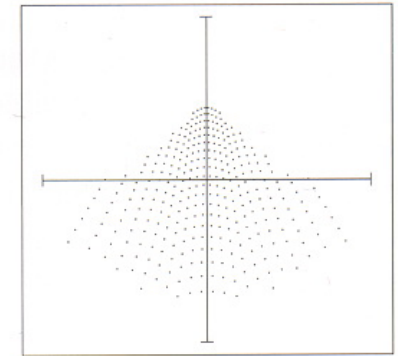


Figure-8

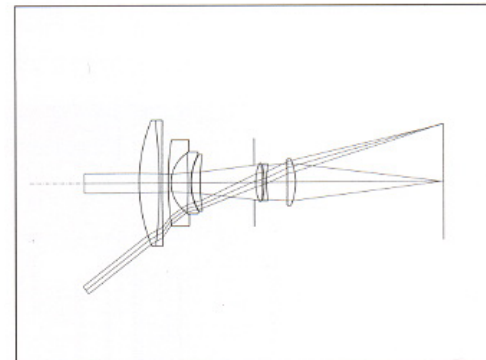


Figure-6

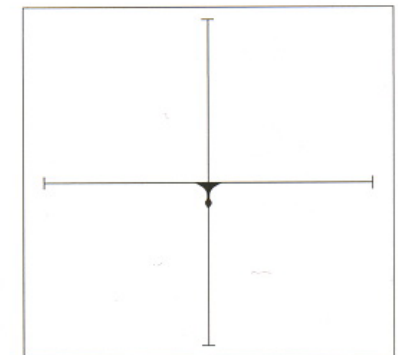


Figure-9

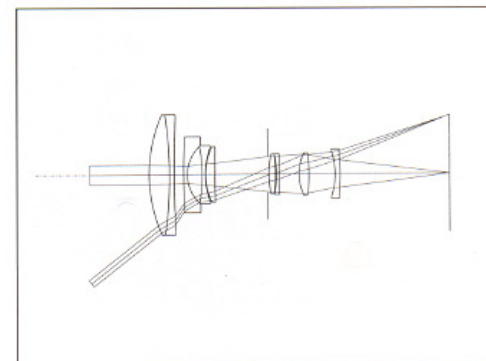


Figure-7

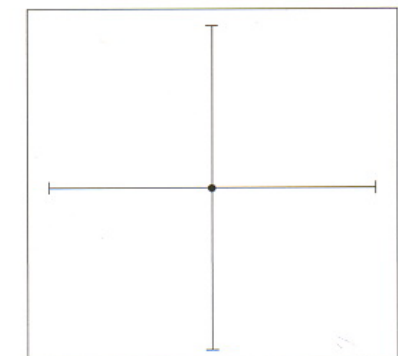


Figure-10

source: canon red book

Optimization

- **Free parameters**
 - Lens curvature, width, position, type of glass
 - Some can be fixed, other vary with focal length, focus (e.g. floating elements)
 - Multiplied by number of lens elements
- **Energy/merit function**
 - MTF, etc.
 - Black art of massaging the merit function
- **Optimize for**
 - All image locations
 - All wavelengths
 - All apertures
 - All focusing distances
 - All focal lengths (zoom only)
- **Usually uses simulated annealing**

Floating elements

- **Move with focus to optimize response (but are not responsible for focusing)**

Figure-32 EF85mm f/1.2L USM Floating System

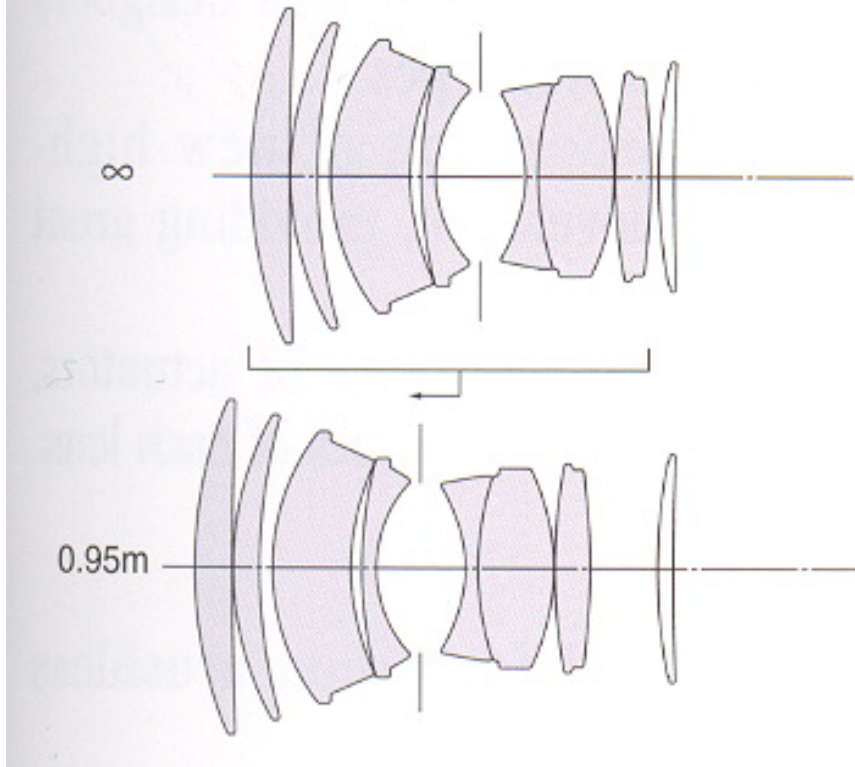


Figure-33 Floating Effect (at 0.95m)

Spherical aberration

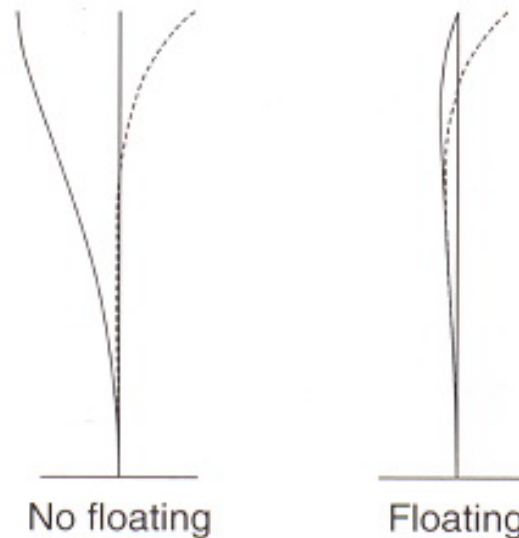
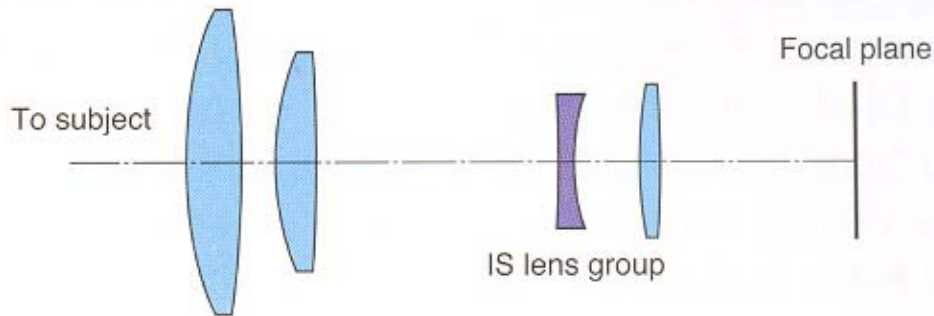




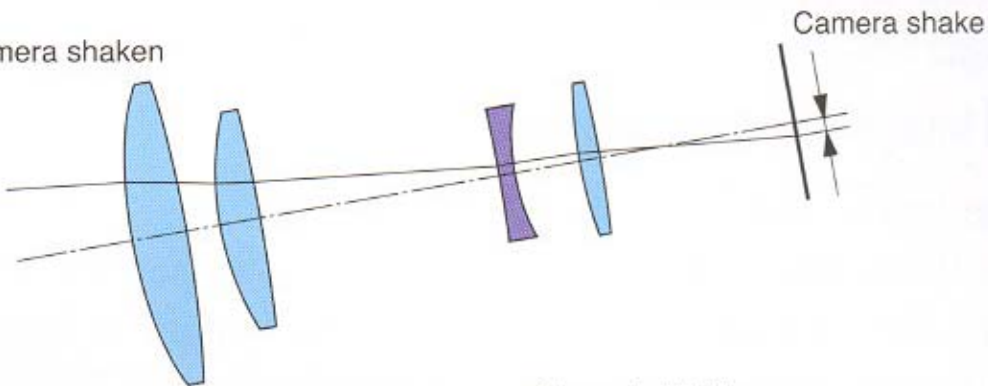
Image stabilization

Image stabilization

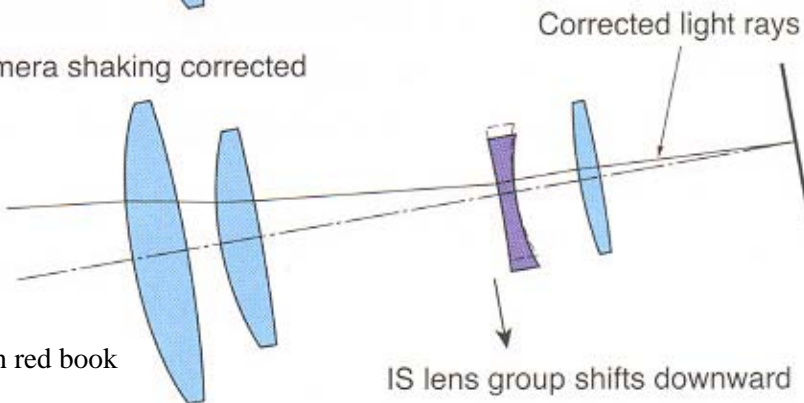
1. Lens when still



2. Camera shaken



3. Camera shaking corrected



source: canon red book

Photo-21 Shake-detecting gyro sensor

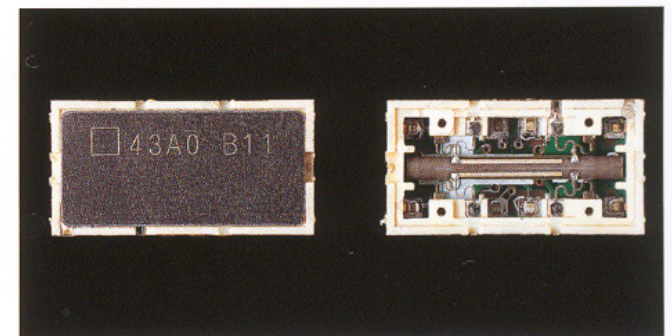
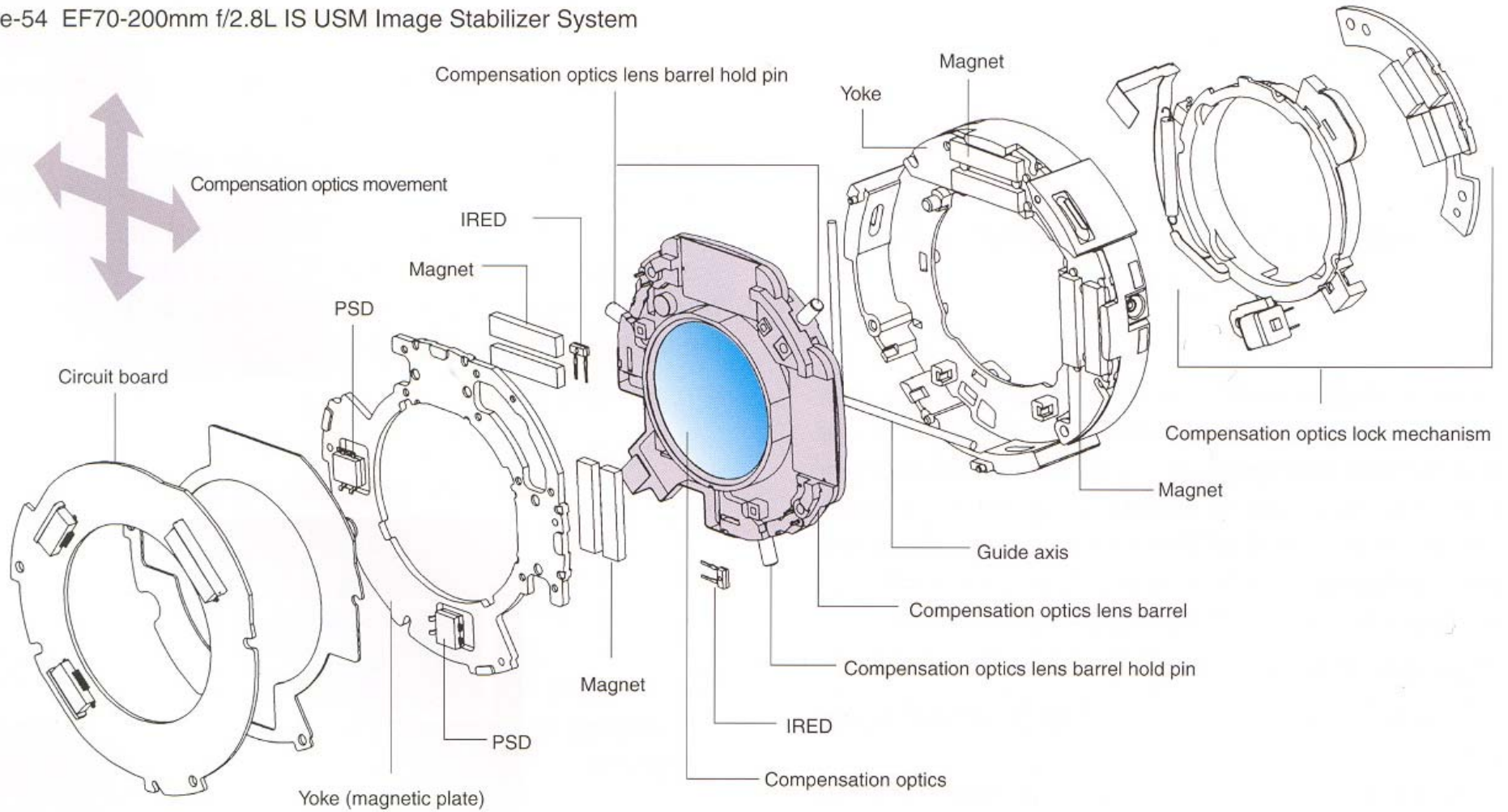


Image stabilization

Figure-54 EF70-200mm f/2.8L IS USM Image Stabilizer System



source: canon red book

Image stabilization



source: canon red book

1000mm, 1/100s, monopod, IS



Different versions

- **Canon, Nikon: in the lens**
- **Panasonic, Konica/Minolta: move sensor**



6.088 Digital and Computational Photography
6.882 Advanced Computational Photography

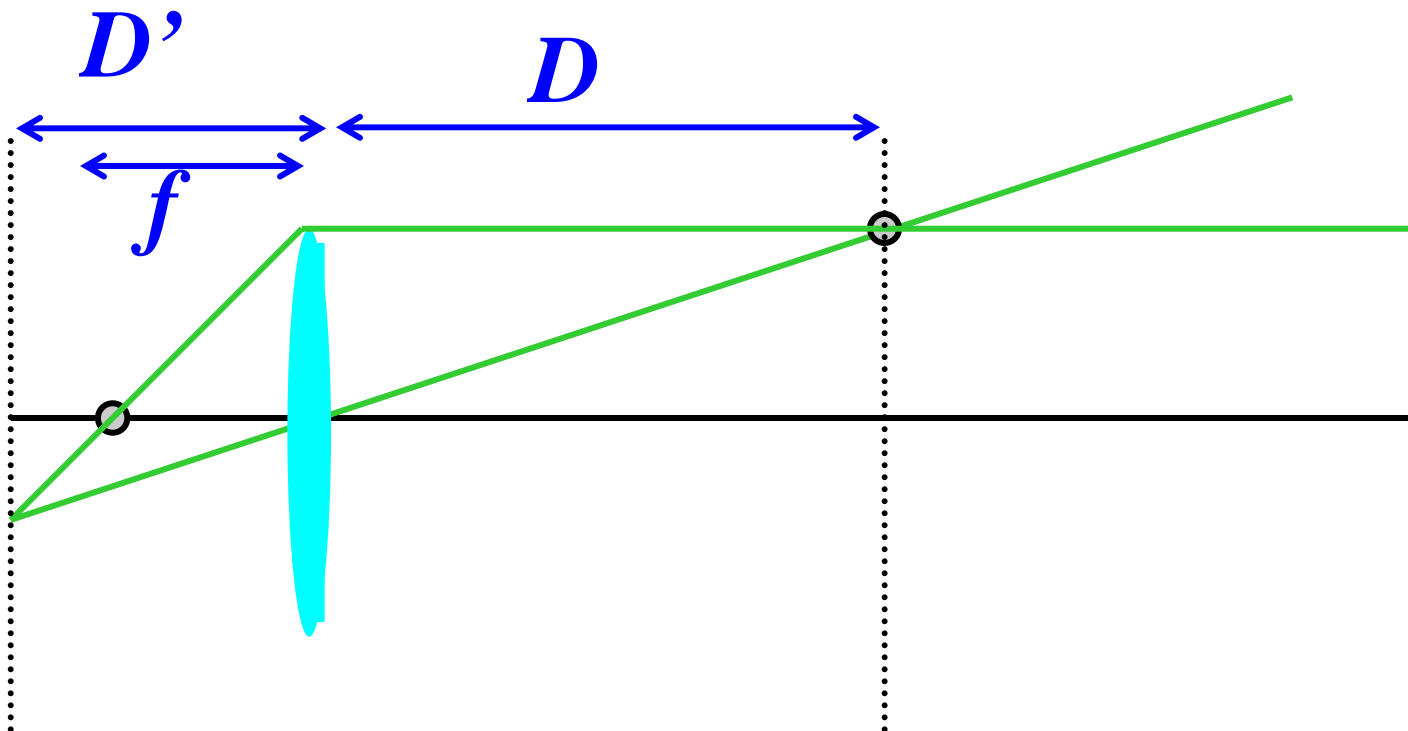
Focus and Depth of Field

Frédo Durand
MIT - EECS

Focusing

- Move film/sensor
- Thin-lens formula

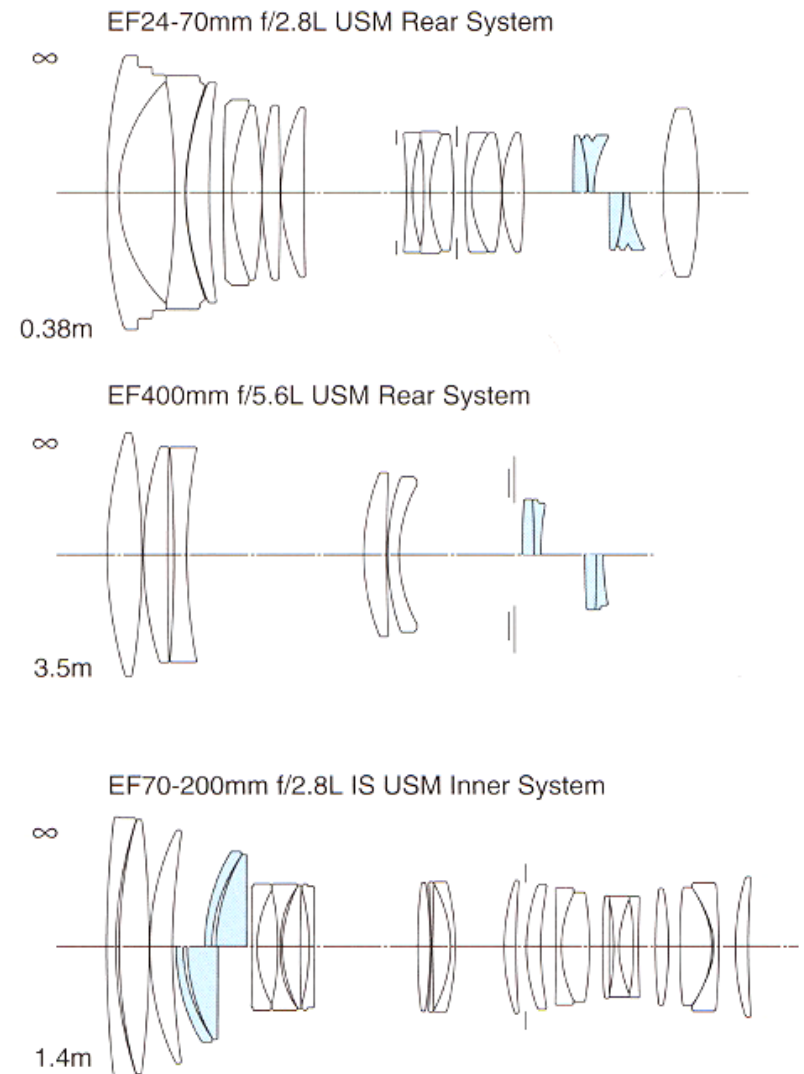
$$\frac{1}{D'} + \frac{1}{D} = \frac{1}{f}$$



In practice, it's a little more complex

- **Various lens elements can move inside the lens**
 - Here in blue

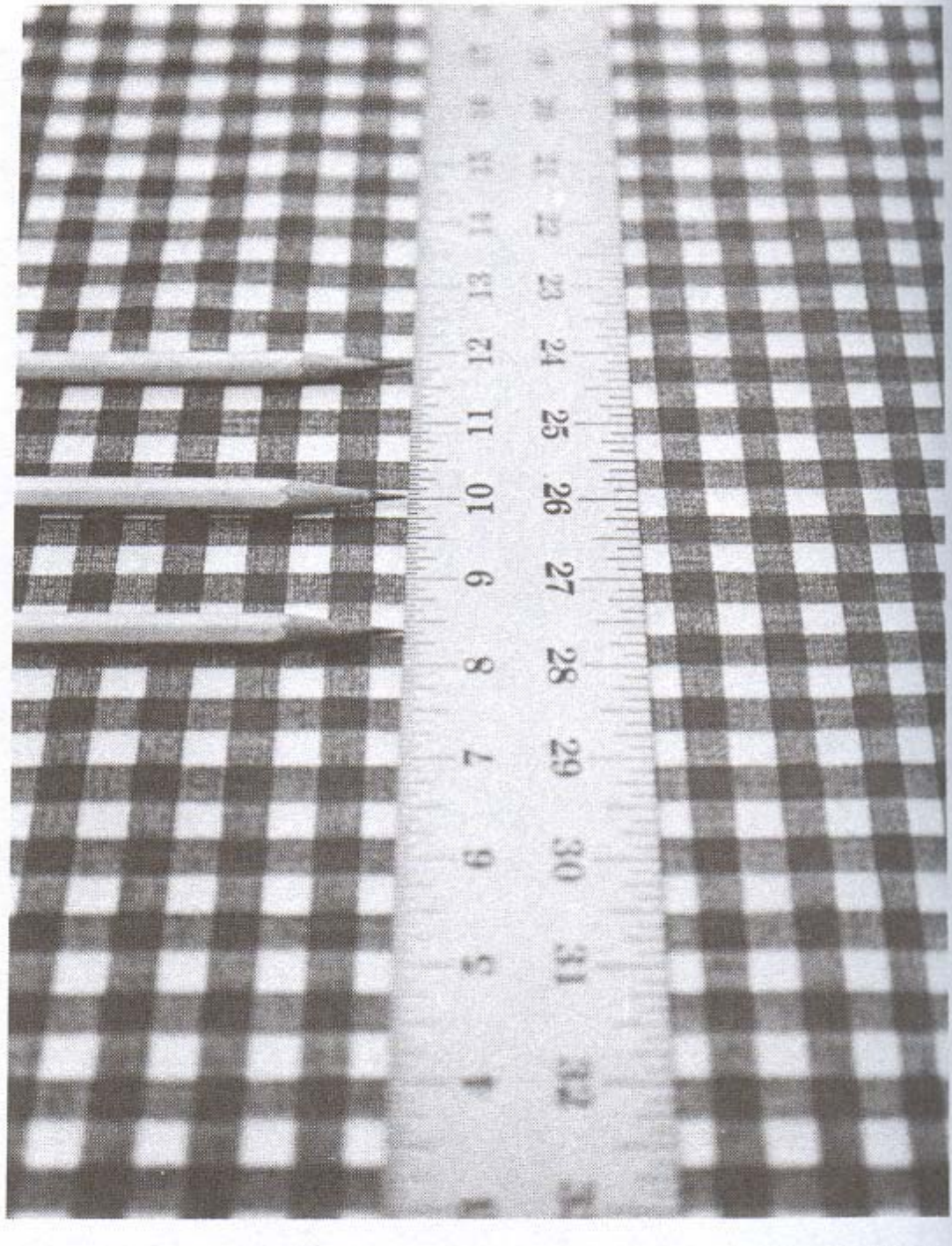
Figure-29 Rear and Inner Focusing Systems



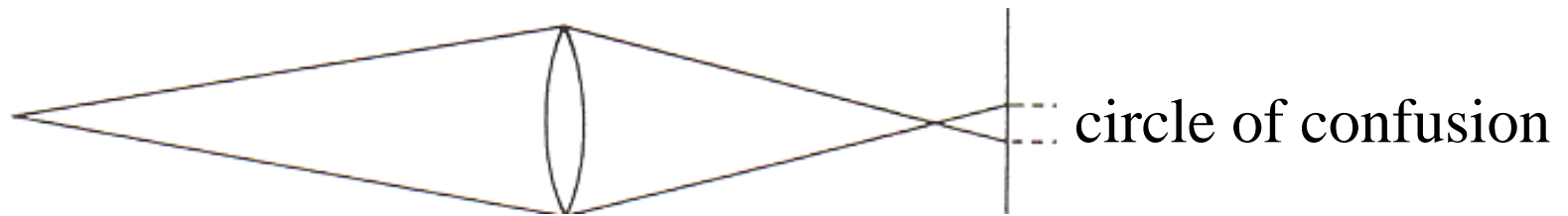
Source: Canon red book.



Defocus & Depth of field



Circle of confusion



Depth of focus

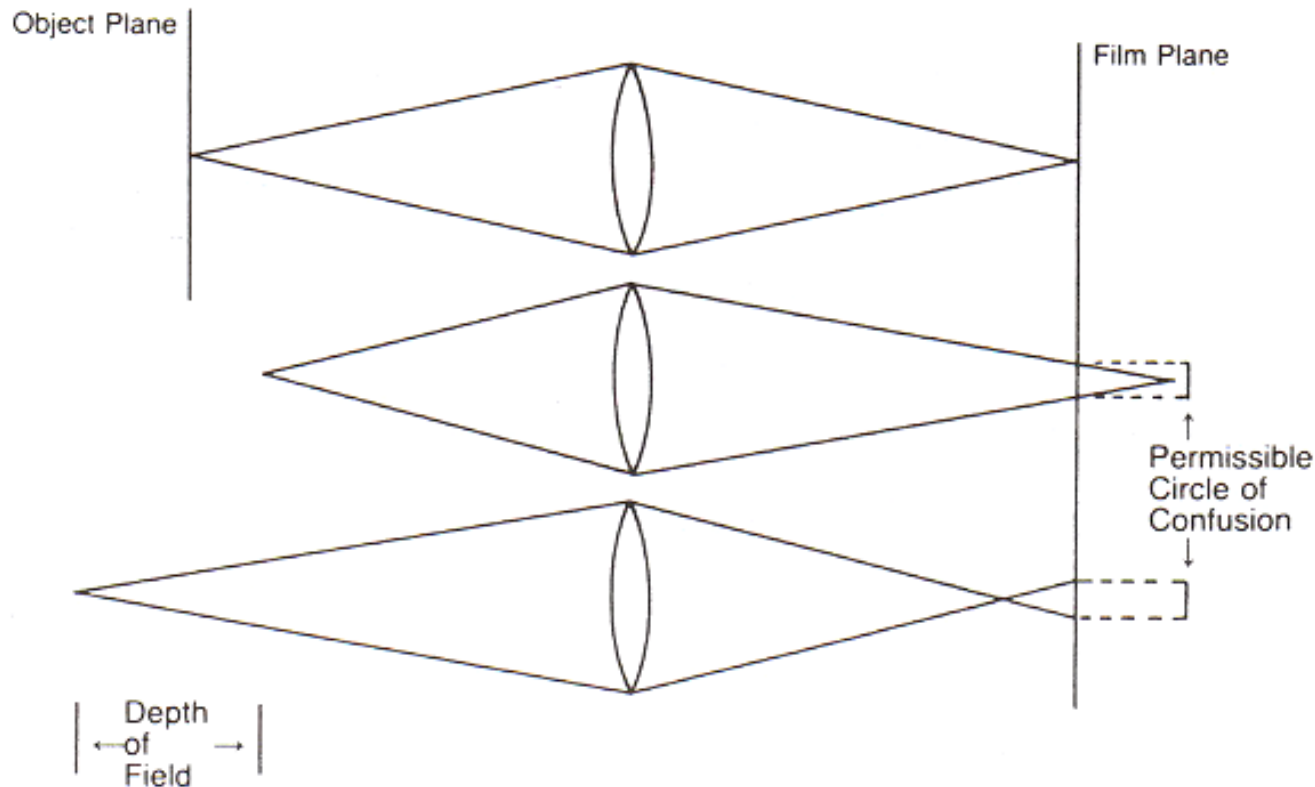


Figure 5-33A Depth of field is the range of distances within which objects are imaged with acceptable sharpness. At the limits, object points are imaged as permissible circles of confusion.

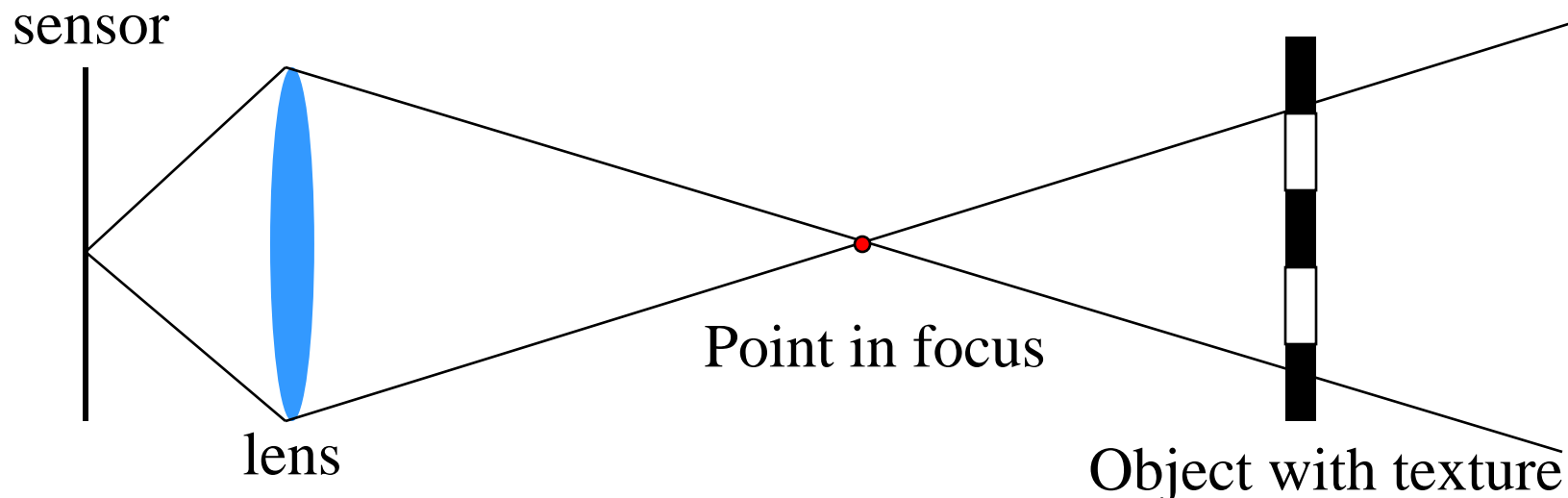
From Basic Photographic Materials and Processes, Stroebel et al.

Size of permissible circle?

- **Assumption on print size, viewing distance, human vision**
 - Typically for 35mm film: diameter = 0.02mm
- **Film/sensor resolution**
(8 μ photosites for high-end SLR)
- **Best lenses are around 60 lp/mm**
- **Diffraction limit**

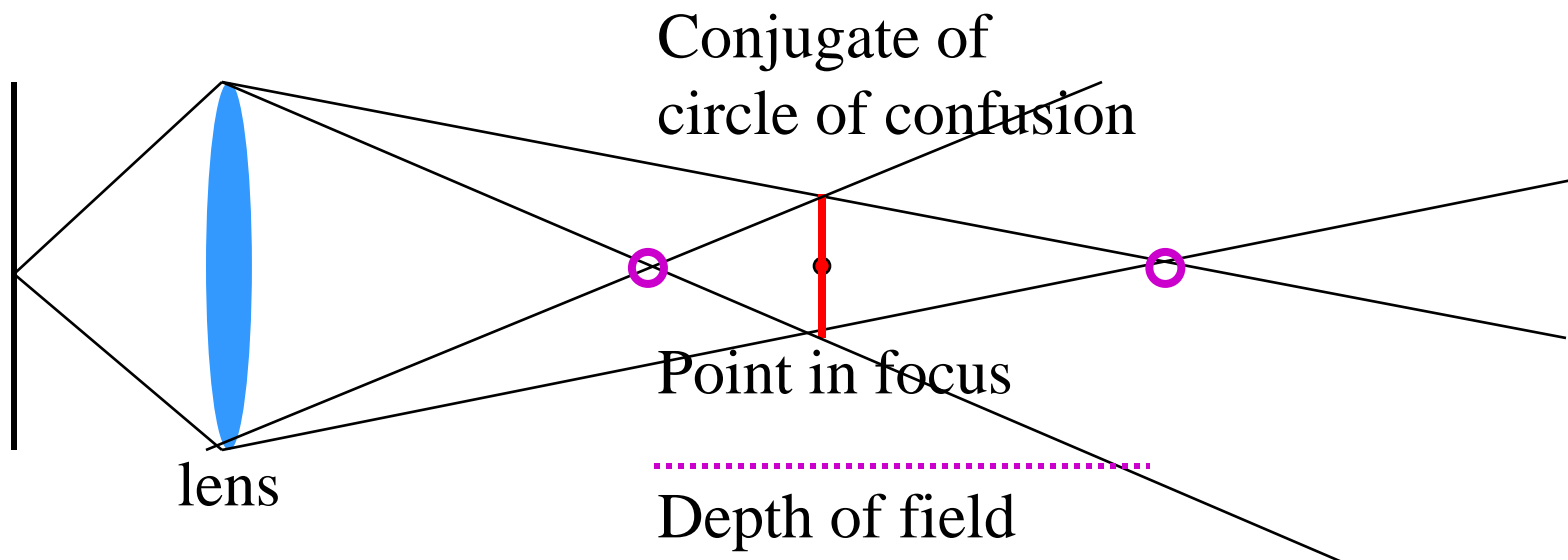
Depth of field: Object space

- **Simplistic view: double cone**
 - Only tells you about the value of one pixel
 - Things are in fact a little more complicated to assess circles of confusion across the image
 - We're missing the magnification factor (proportional to $1/\text{distance}$ and focal length)



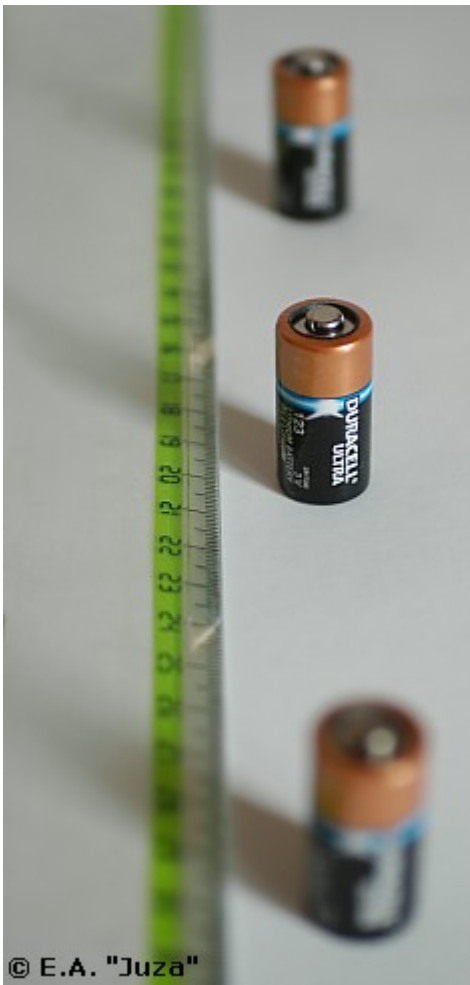
Depth of field: more accurate view

- **Backproject the image onto the plane in focus**
 - Backproject circle of confusion
 - Depends on *magnification factor*
- **Depth of field is slightly asymmetrical**

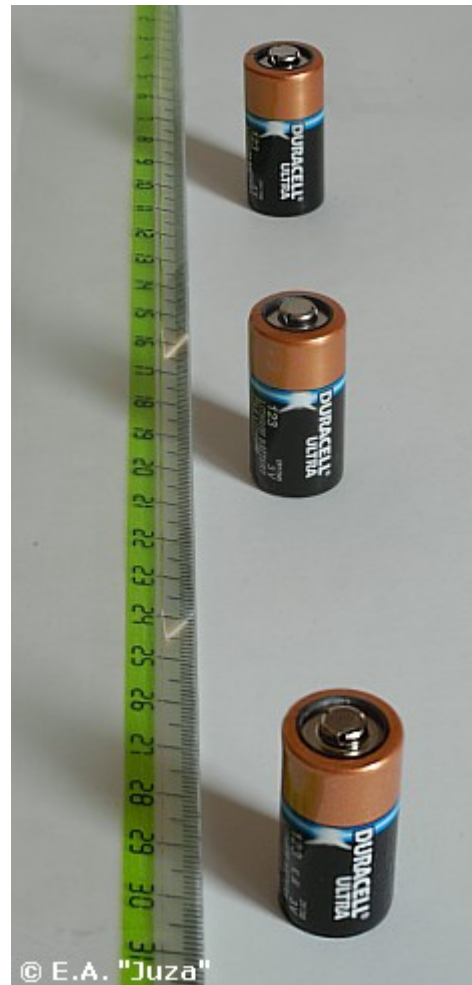


DoF & aperture

- http://www.juzaphoto.com/eng/articles/depth_of_field.htm



f/2.8

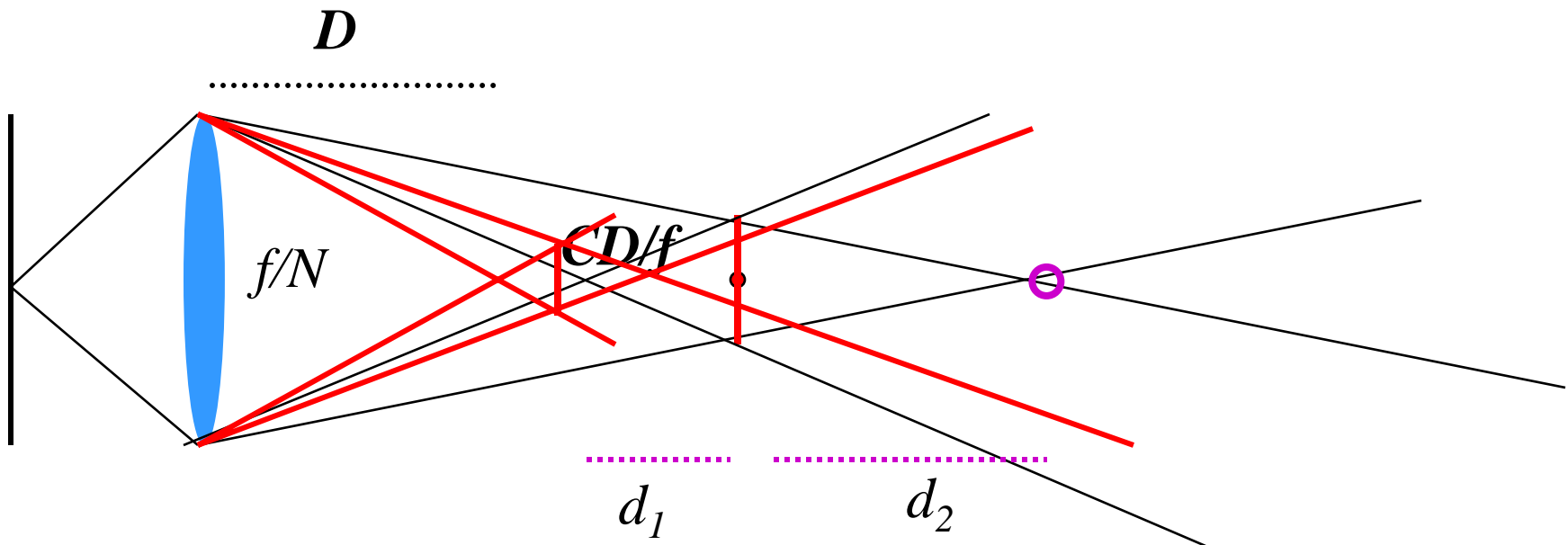


f/32

Depth of field and focusing distance

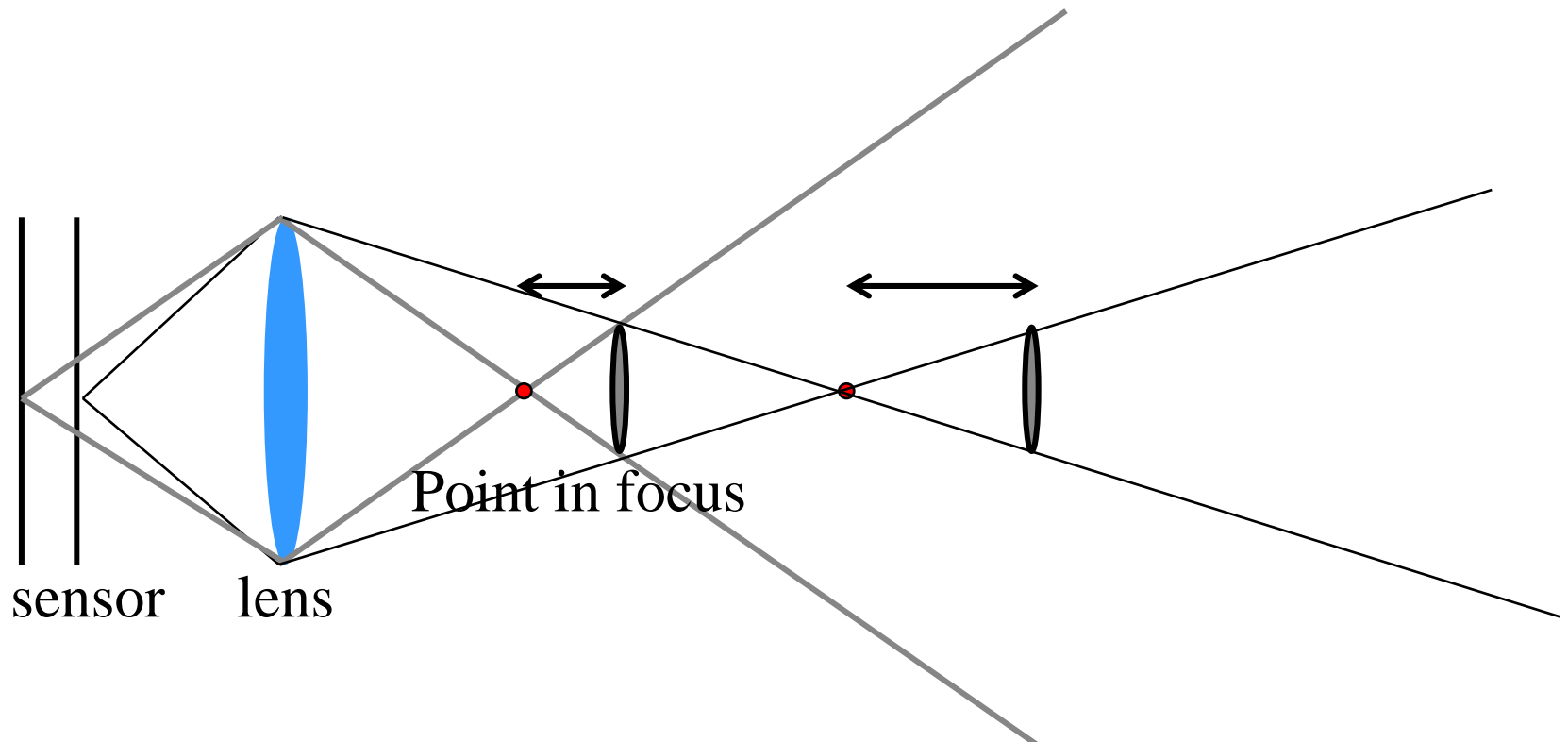
- Quadratic (bad news for macro)
(but careful, our simplifications
are not accurate for macro)

$$d = \frac{2NC \boxed{D^2}}{f^2}$$

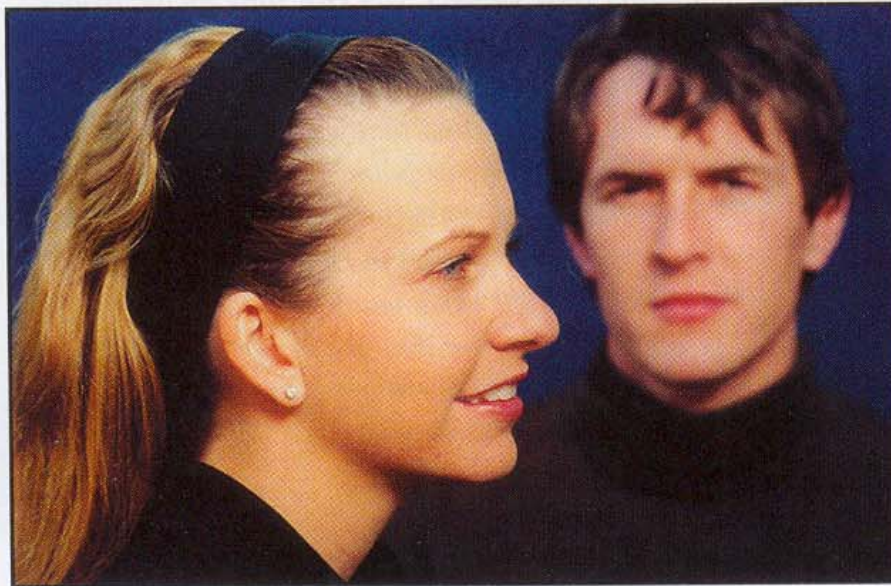


Double cone perspective

- Seems to say that relationship is linear
- But if you add the magnification factor, it's actually quadratic



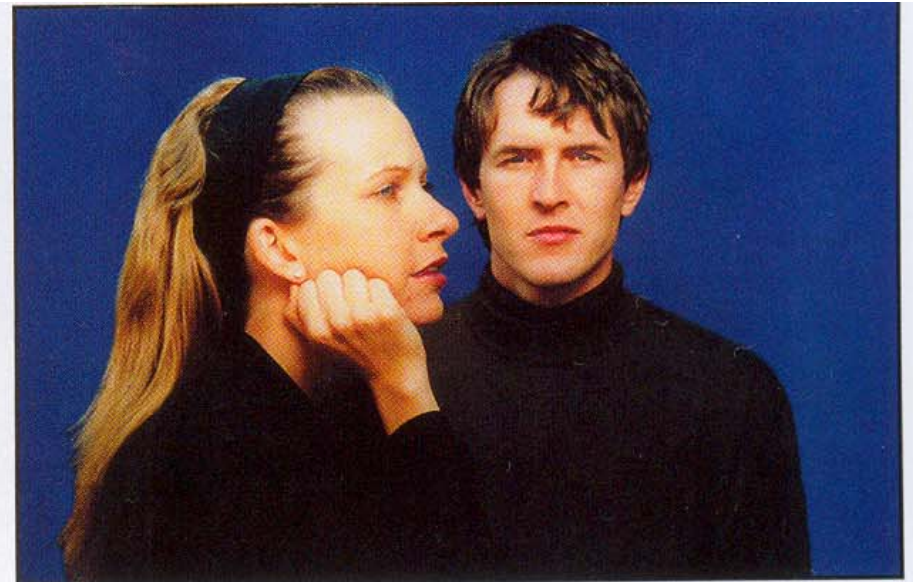
Depth of field & focusing distance



Closer to subject



3 feet



Farther from subject

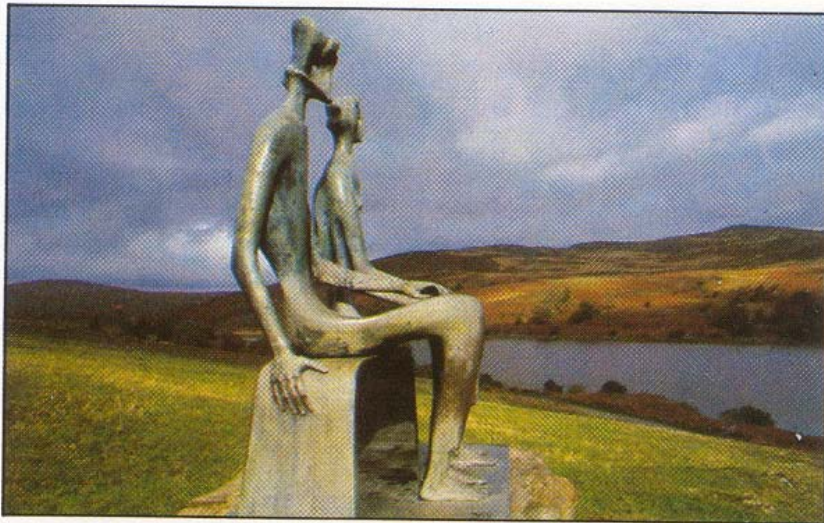


10 feet

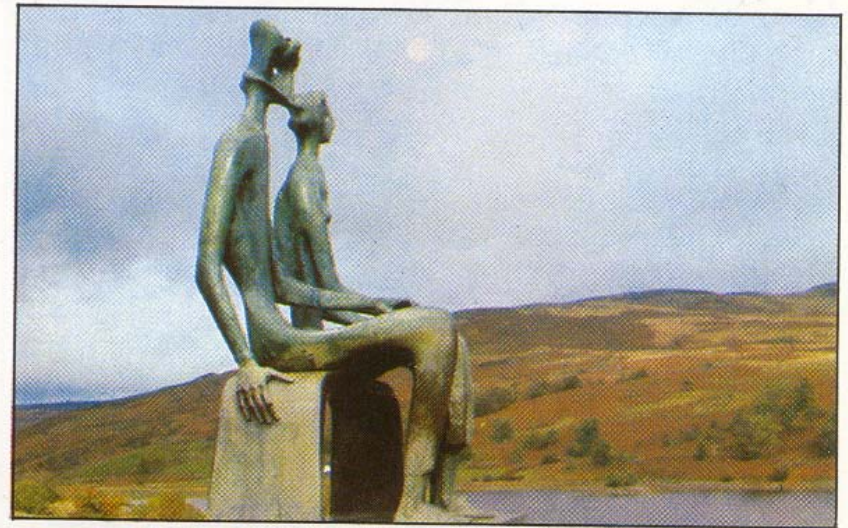
From Photography, London et al.

Depth of field & focal length

- Recall that to get the same image size, we can double the focal length and the distance
- Recall what happens to physical aperture size when we double the focal length for the same f number?
 - It is doubled



24mm

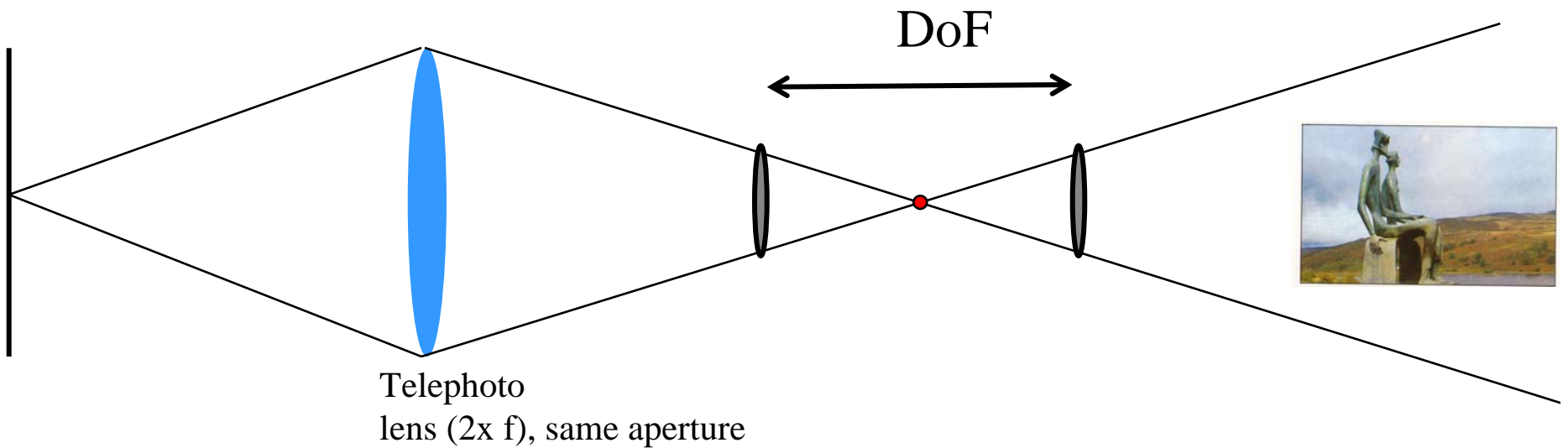
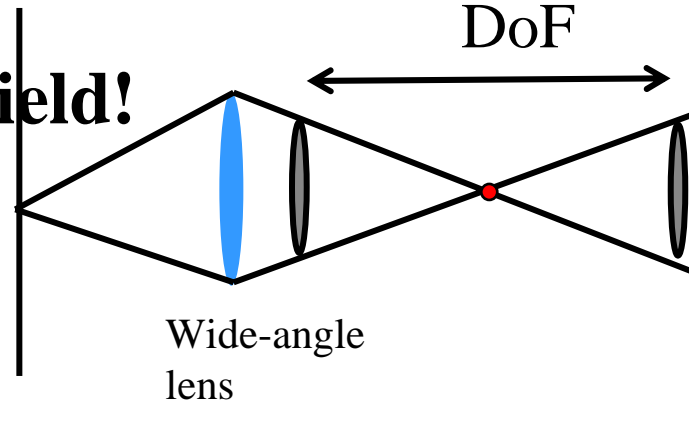


50mm

Depth of field & focal length

- Same image size (same magnification)
same f number
- Same depth of field!

$$d = \frac{2NcD^2}{f^2}$$



DoF & Focal length

- http://www.juzaphoto.com/eng/articles/depth_of_field.htm



50mm f/4.8



200mm f/4.8
(from 4 times farther)

See also <http://luminous-landscape.com/tutorials/dof2.shtml>

Important conclusion

- **For a given image size and a given f number, the depth of field (in object space) is the same.**
- **Might be counter intuitive.**
- **Very useful for macro where DoF is critical. You can change your working distance without affecting depth of field**
- **Now what happens to the background blur far far away?**

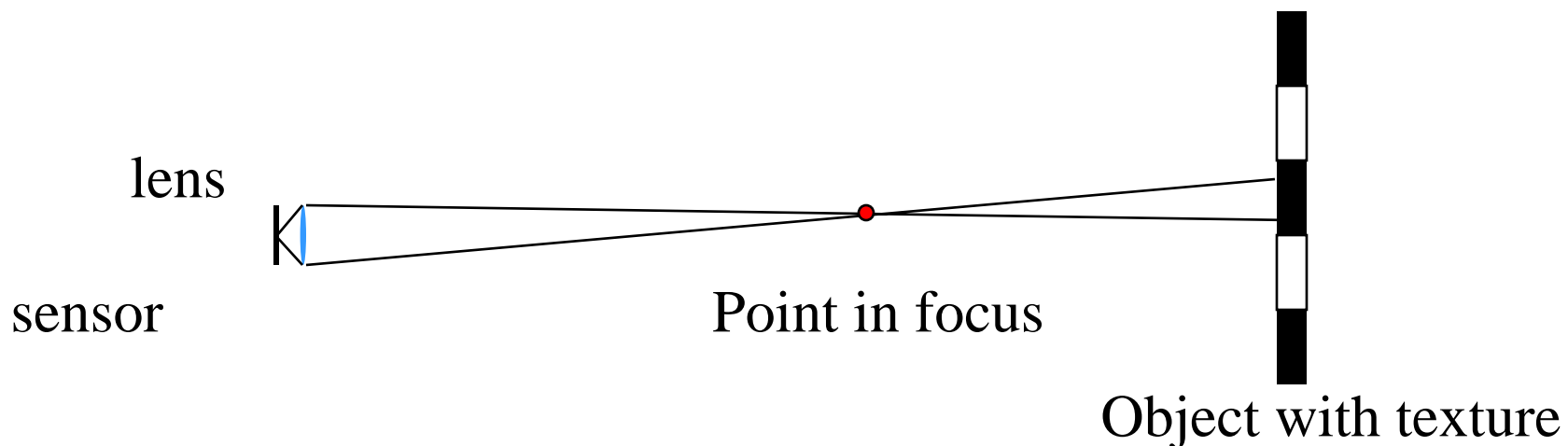
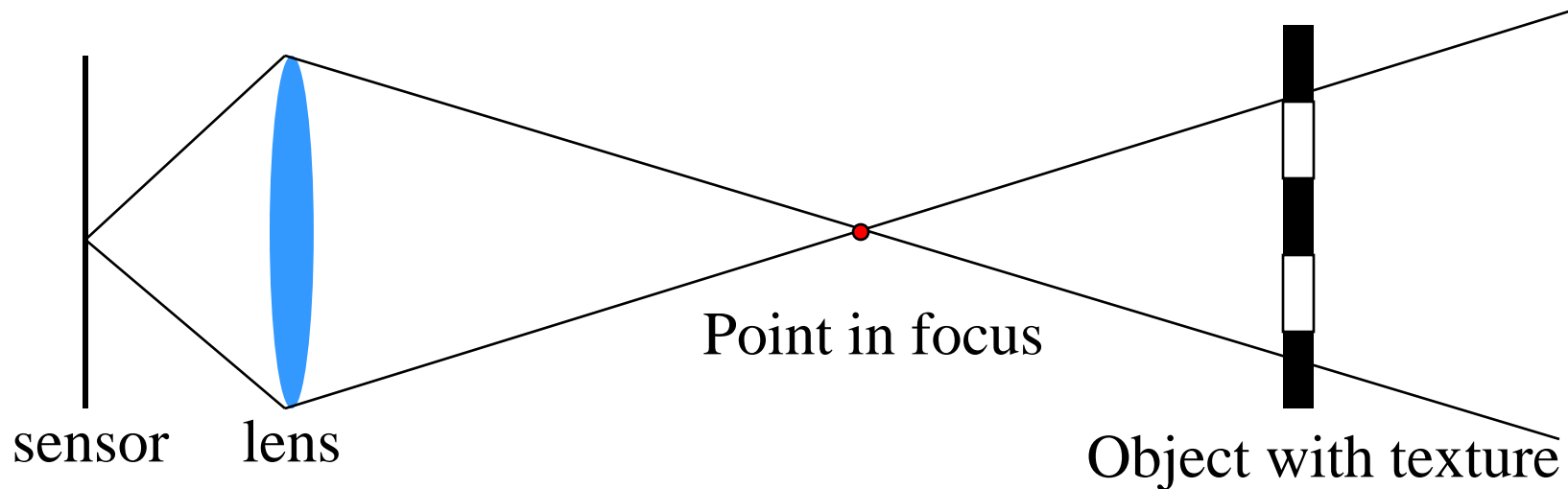


Sensor size



Depth of field

- It's all about the size of the lens aperture



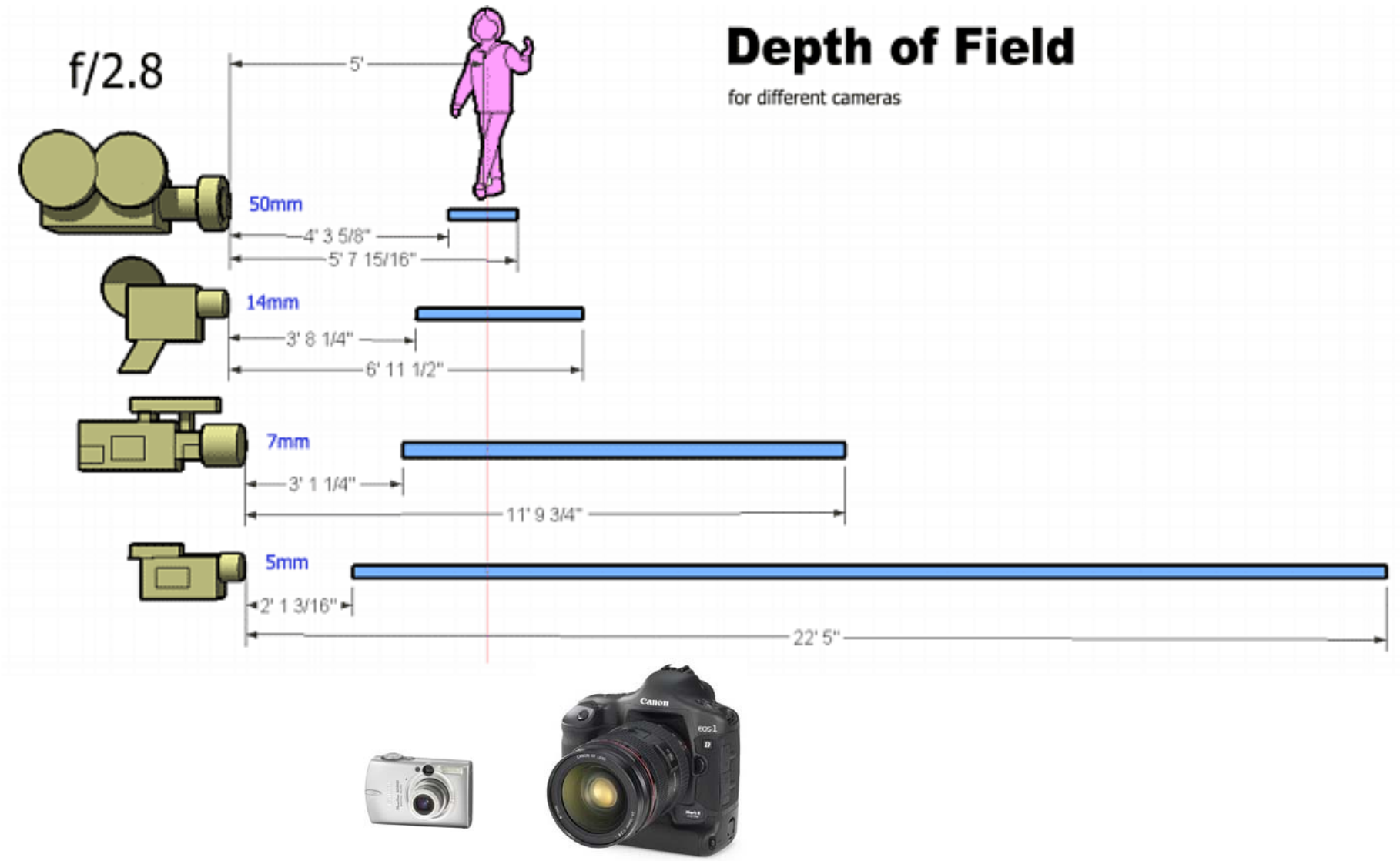
Equation

- **Smaller sensor**
 - smaller C
 - smaller f
- **But the effect of f is quadratic**

$$d = \frac{2NCD^2}{f^2}$$

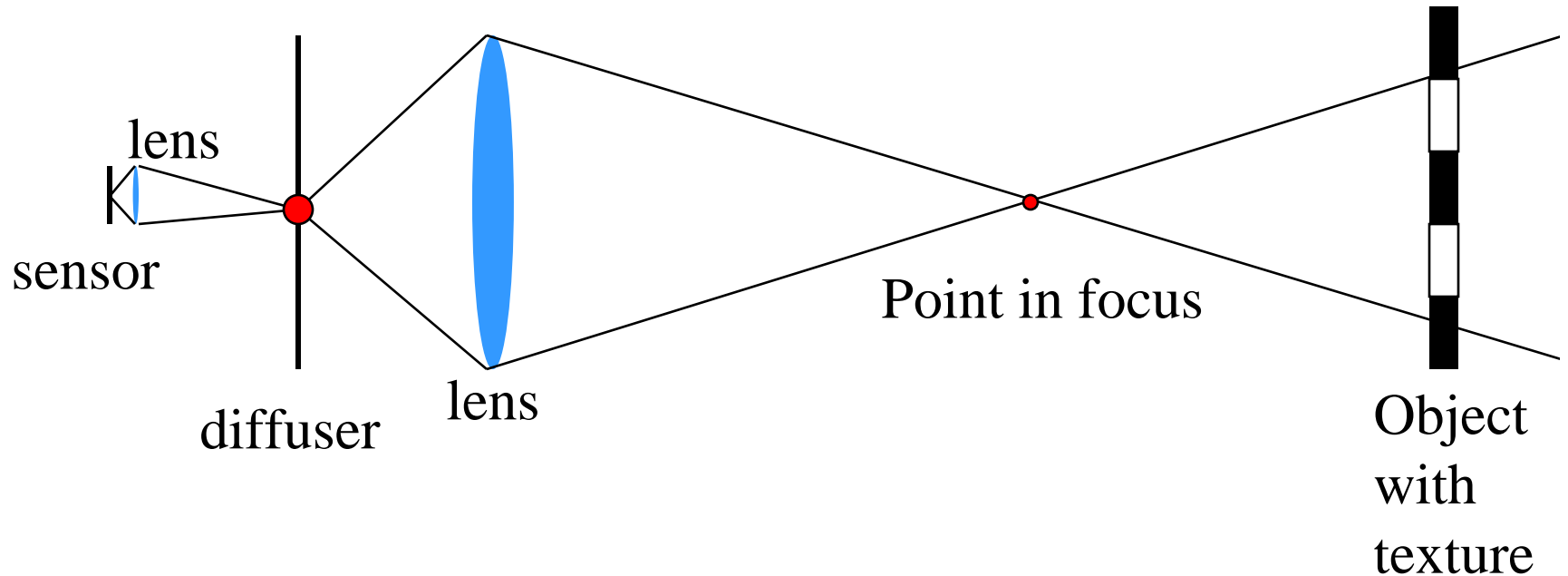
Sensor size

- <http://www.mediachance.com/dvdlab/dof/index.htm>



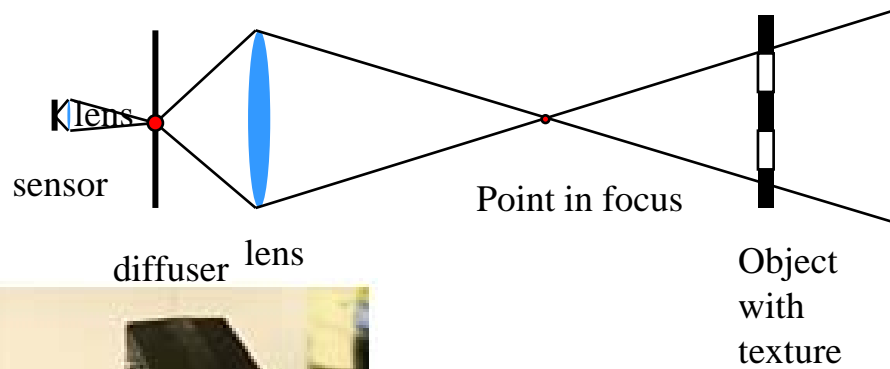
The coolest depth of field solution

- <http://www.mediachance.com/dvdlab/dof/index.htm>
- Use two optical systems



The coolest depth of field solution

- <http://www.mediachance.com/dvdlab/dof/index.htm>





Seeing through occlusion

Seeing beyond occlusion

- **Photo taken through zoo bars**
- **Telephoto at full aperture**
- **The bars are so blurry that they are invisible**



Synthetic aperture

- **Stanford Camera array (Willburn et al. <http://graphics.stanford.edu/papers/CameraArray/>)**

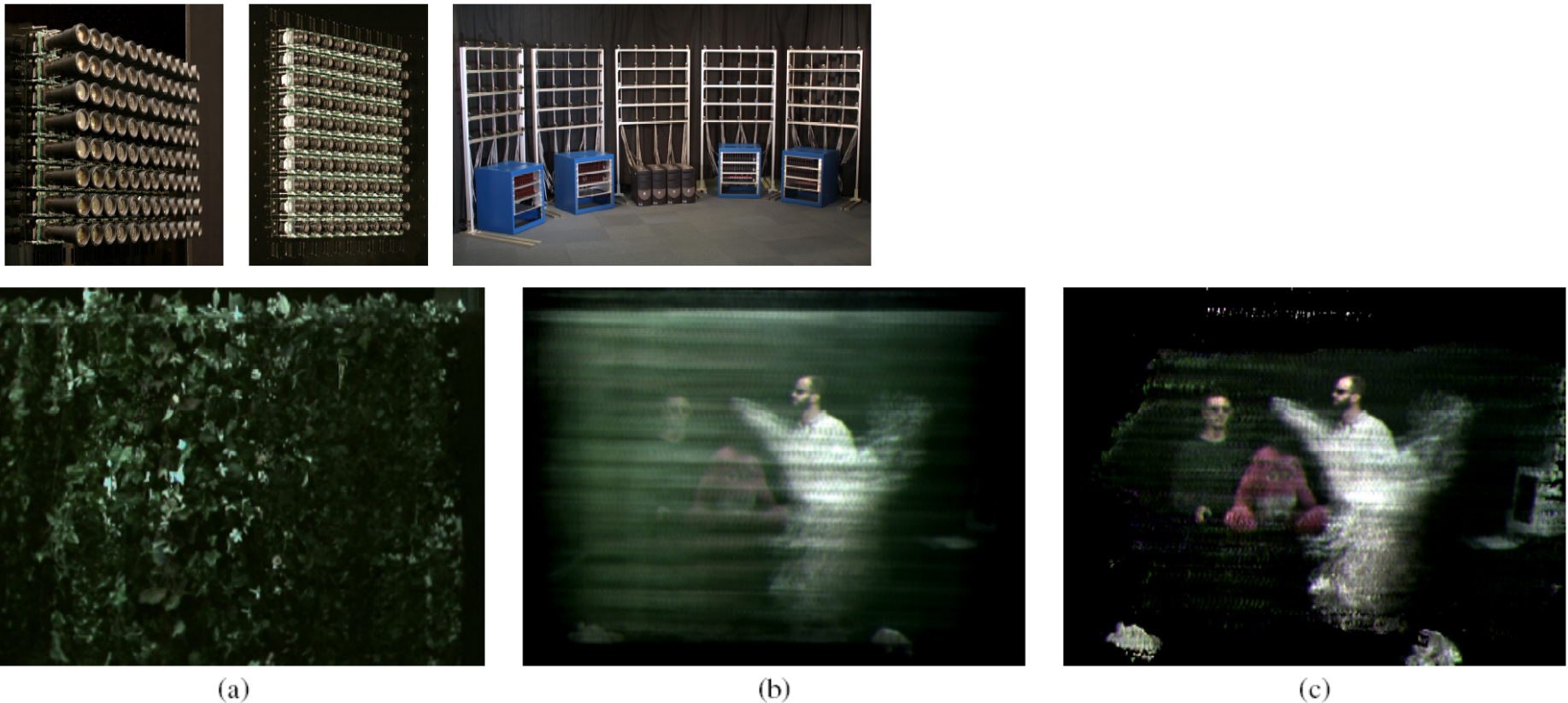


Figure 11: Matted synthetic aperture photography. (a) A sample image from one of 90 cameras used for this experiment. (b) The synthetic aperture image focused on the plane of the people, computed by aligning and averaging images from all 90 cameras as described in the text. (c) Suppressing contributions from static pixels in each camera yields a more vivid view of the scene behind the occluder. The person and stuffed toy are more clearly visible.



Autofocus

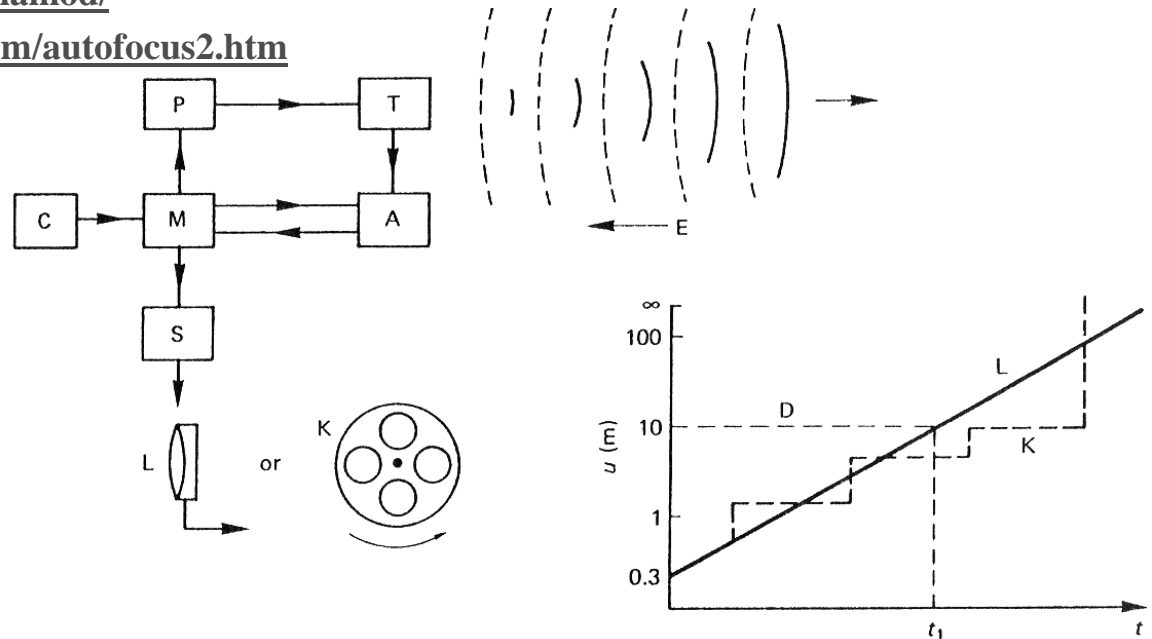




How would you build an Auto Focus?

Polaroid Ultrasound (Active AF)

- Time of flight (sonar principle)
- Limited range, stopped by glass
- Paved the way for use in robotics
- <http://www.acroname.com/robotics/info/articles/sonar/sonar.html>
- <http://www.uoxray.uoregon.edu/polamod/>
- <http://electronics.howstuffworks.com/autofocus2.htm>



<http://www.uoxray.uoregon.edu/polamod/>

Figure 21.3 Polaroid sonar autofocus

Ultrasonic pulse emitted by transducer T from power unit P under control of microprocessor M and clock C. Echo E also received by T, digitized by analogue-digital circuitry A, returns to M to control focusing motor S. This halts axial movement of lens L or a rotation of disc K of supplementary lenses behind L. Graph of elapsed time t against u shows focusing behaviour.

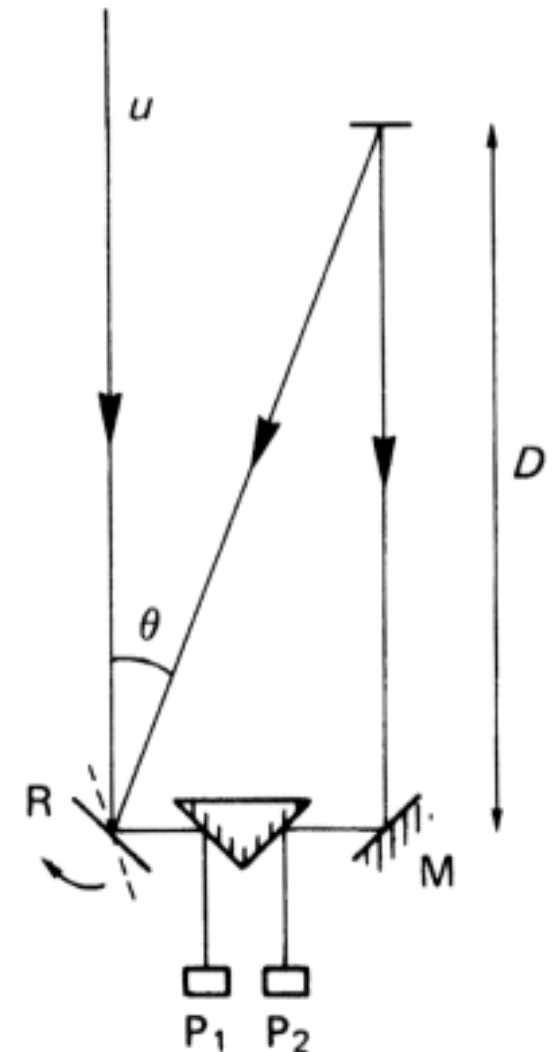
From Ray's Applied Photographic Optics

Infrared (Active AF)

- **Intensity of reflected IR is assumed to be proportional to distance**
- **There are a number of obvious limitations**
- **Advantage: works in the dark**
- **This is different from Flash assistant for AF where the IR only provides enough contrast so that standard passive AF can operate**

Triangulation

- **Rotating mirror sweeps the scene until the image is aligned with fixed image from mirror M**
 - pretty much stereovision and window correlation)



From The Manual of Photography

Different types of autofocus

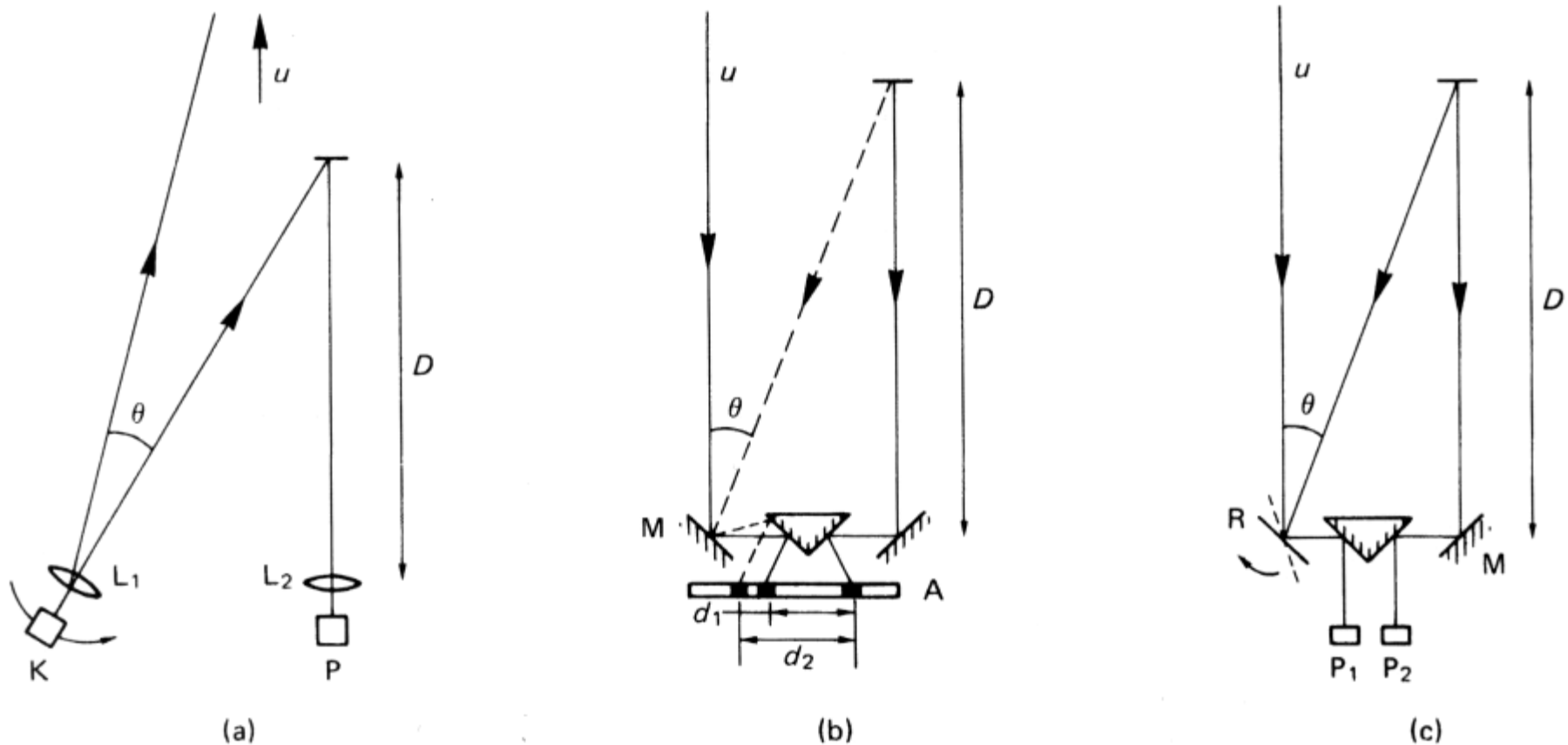
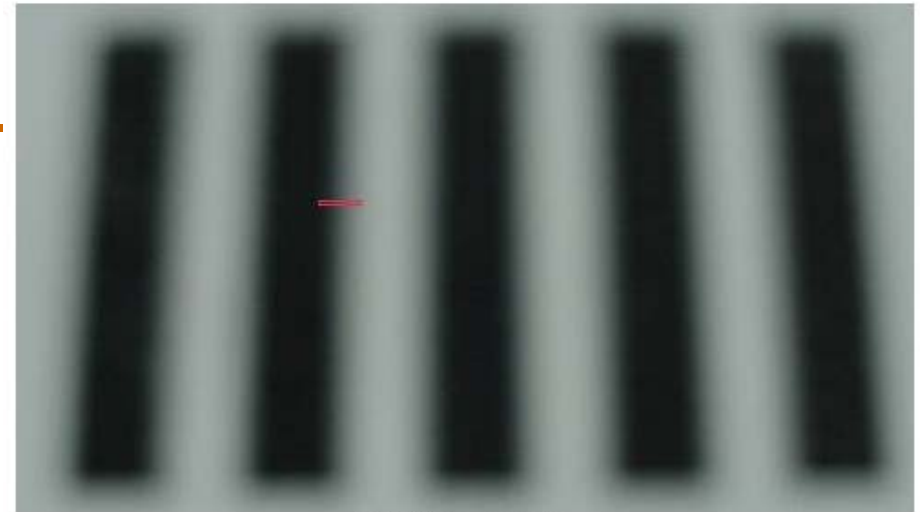


Figure 9.23 Ranging systems for autofocus cameras. (a) Scanning IR-emitting diode K with aspheric lenses L_1 and L_2 and photocell P . (b) Static system with linear CCD array A . The correlated images at separations d_1 and d_2 correspond to distances u and D respectively. (c) Scanning mirror R to correlate images on twin photocells P_1 and P_2

Contrast

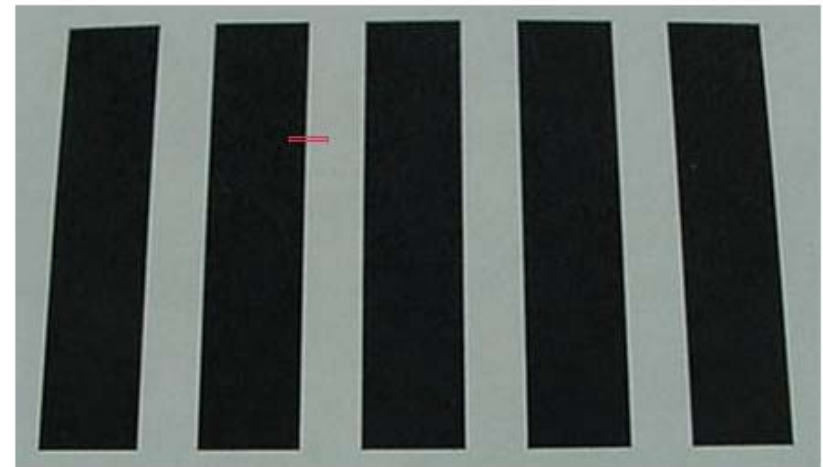
- **Focus = highest contrast**



Out-of-focus scene



Out-of-focus pixel strip



In-focus scene



In-focus pixel strip

Phase detection focusing

- Used e.g. in SLRs

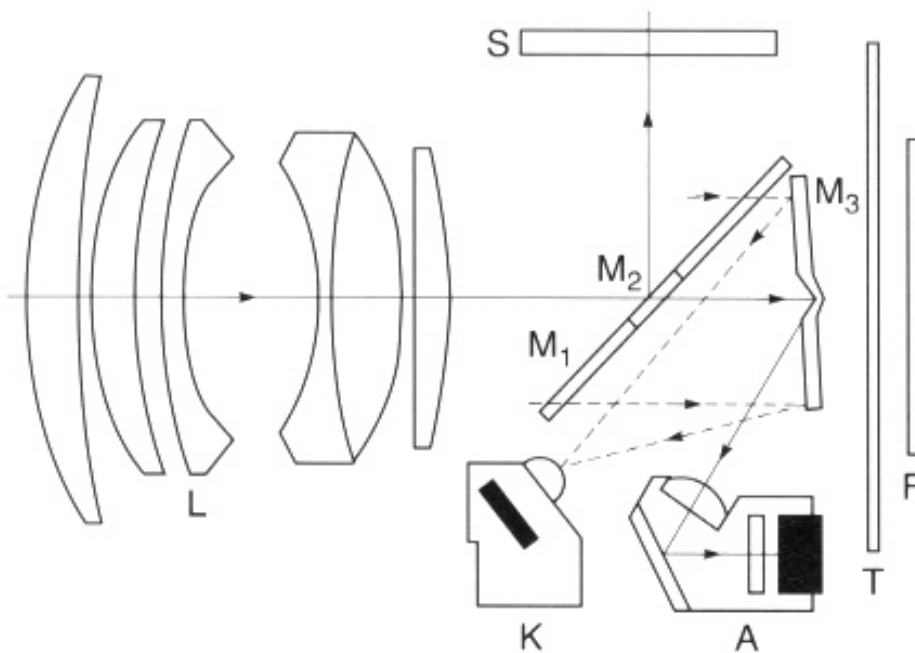
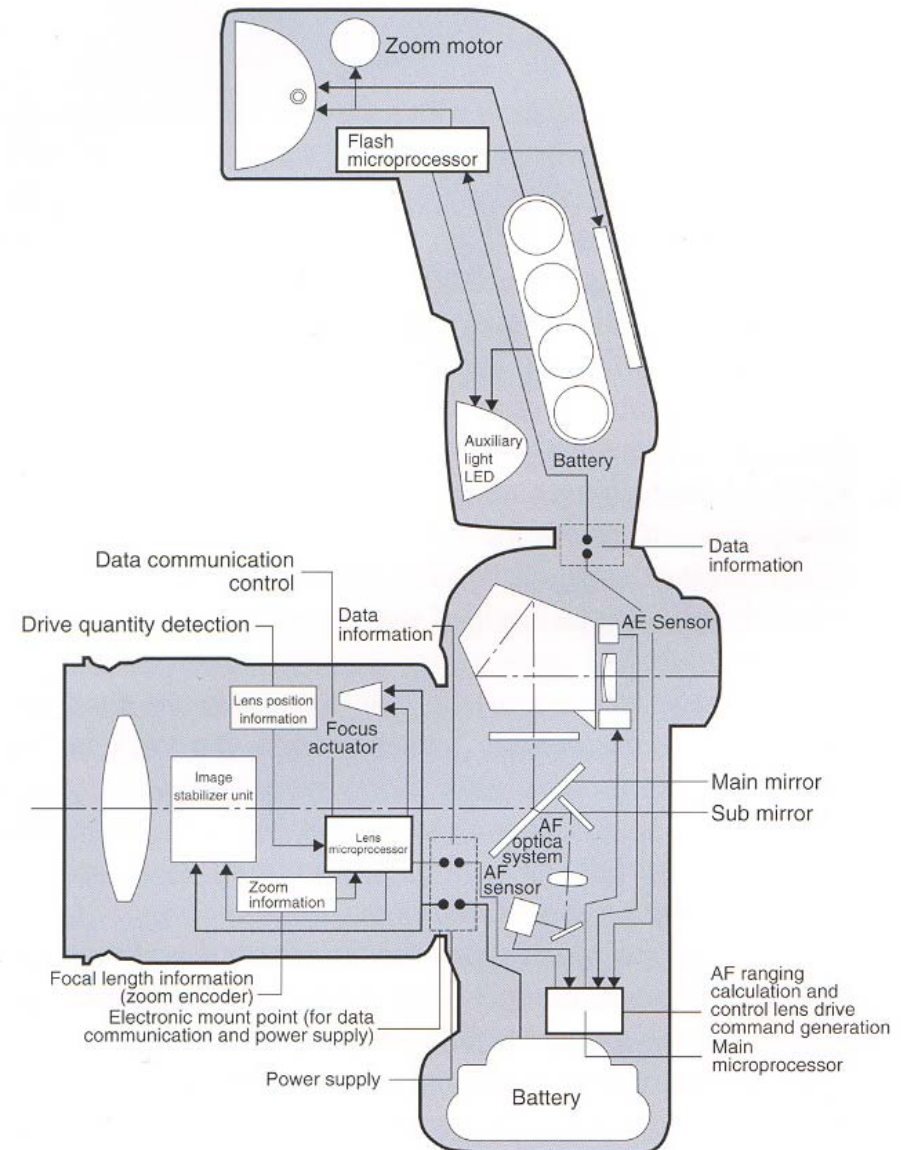


Figure 9.24 Location of autofocus and metering modules. L, camera lens; S, focusing screen; F, film in gate; M_1 , reflex mirror with 30 per cent transmission; M_2 , central region with 50 per cent transmission; M_3 , secondary mirror with two focusing regions; A, autofocus module; K, metering module; spot or centre-weighted

From The Manual of Photography



From the Canon red book

Phase detection focusing

- Stereo vision from two portions of the lens on the periphery
- Not at the equivalent film plane but farther → can distinguish too far and too close
- Look at the phase difference between the two images

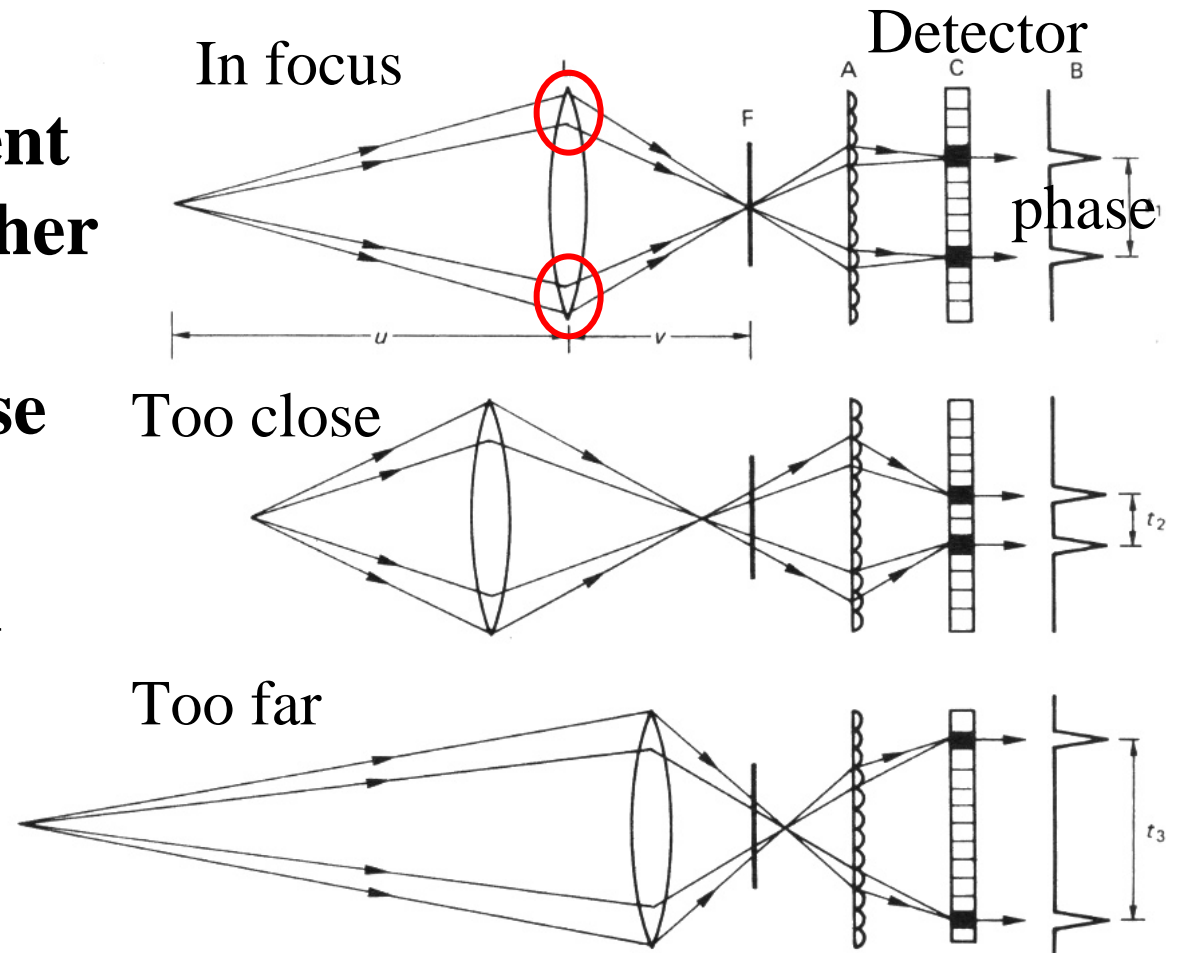
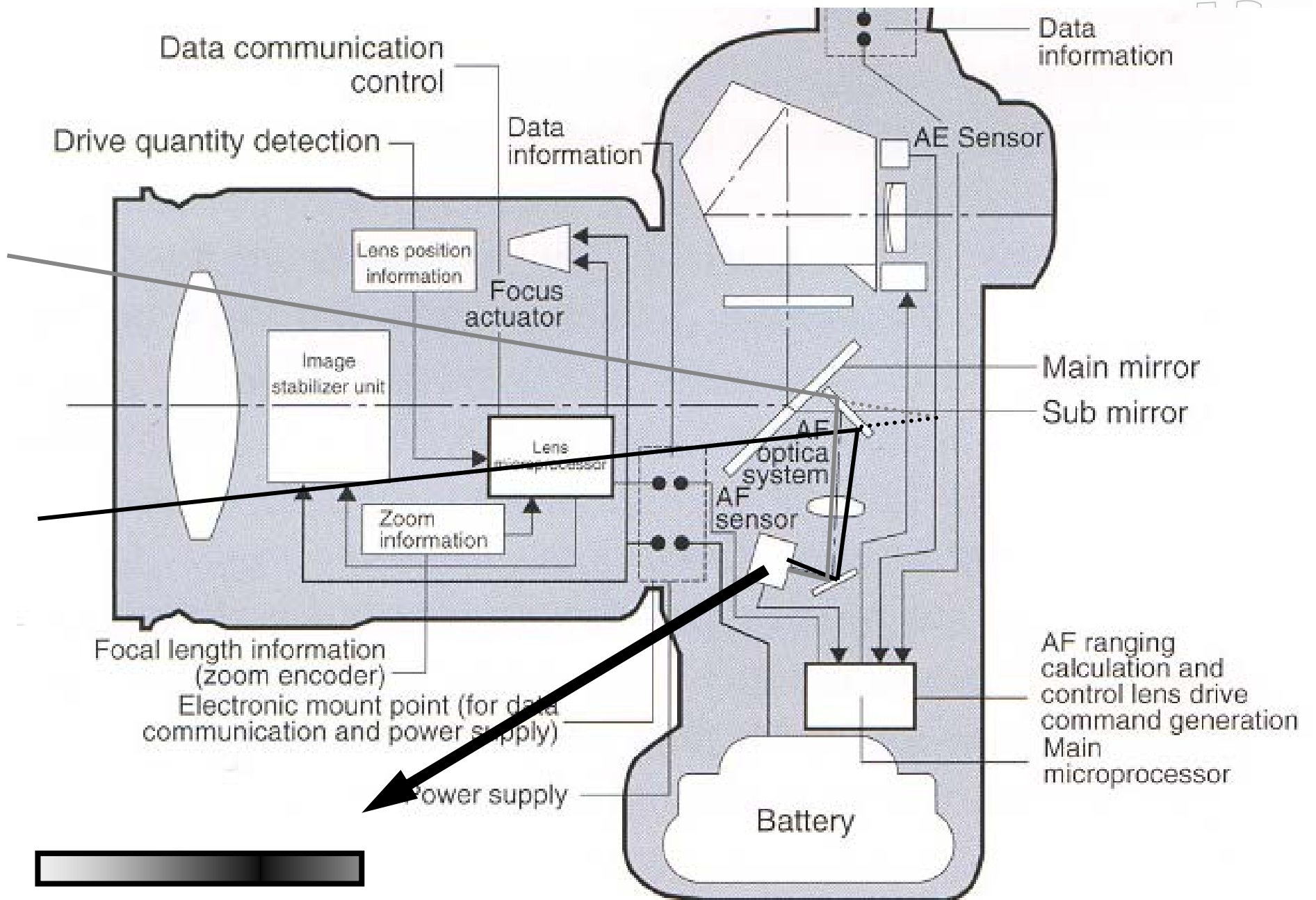


Figure 9.25 Principles of autofocus by phase detection. (a) Subject in focus. (b) Focus in front of subject. (c) Focus beyond subject. Key: L camera lens; F equivalent focal plane; A lenslet array; C CCD linear array; B output signals with time delay t_1 etc.



**compute phase difference,
deduce distance**

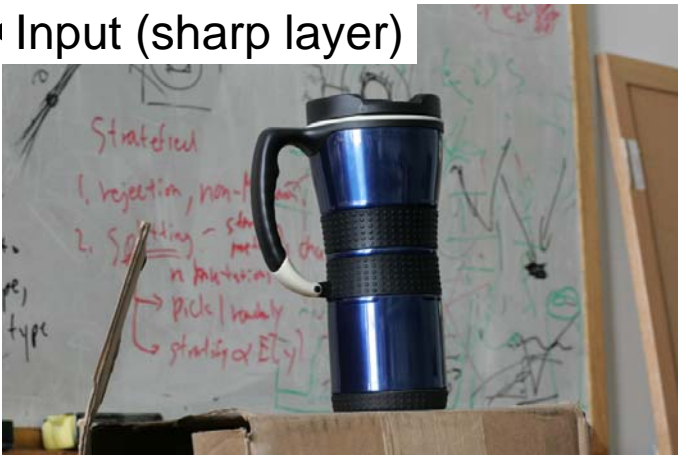


Fake Depth of Field

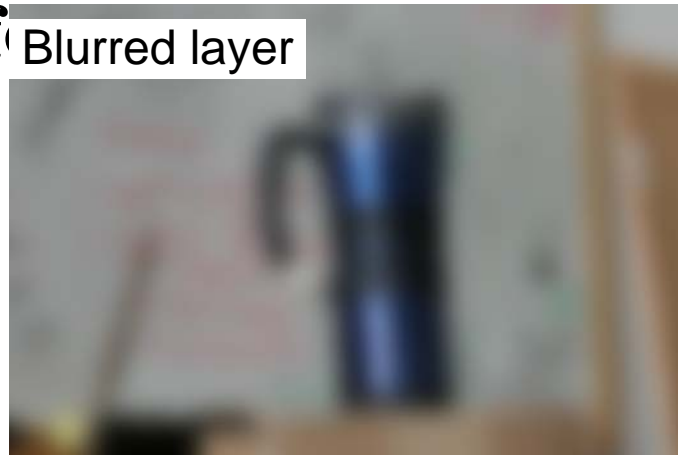
Photoshop

- Using layers:
- One sharp layer, one blurry layer (using Gaussian blur)

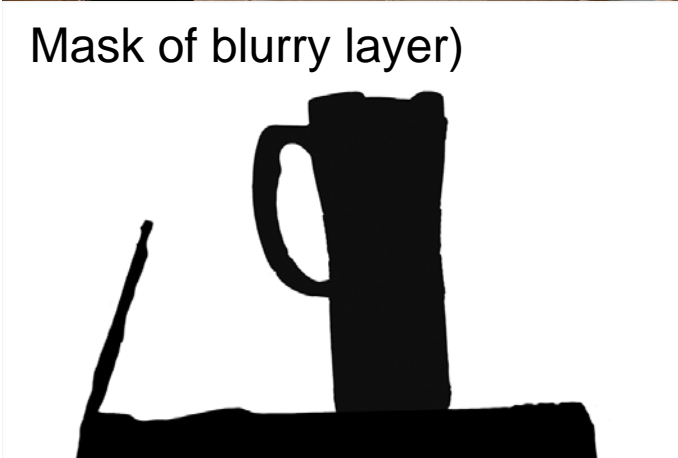
(Input (sharp layer)



(Blurred layer



(Mask of blurry layer)



(Result



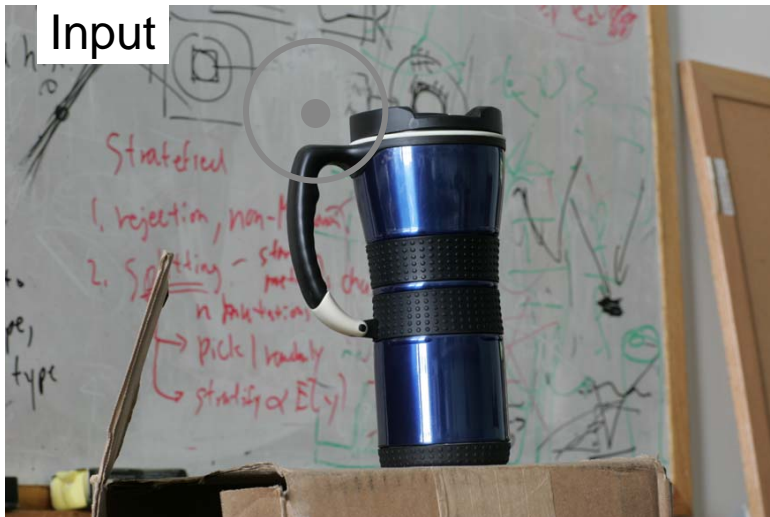
Photoshop

- **Problem: halo around edges**

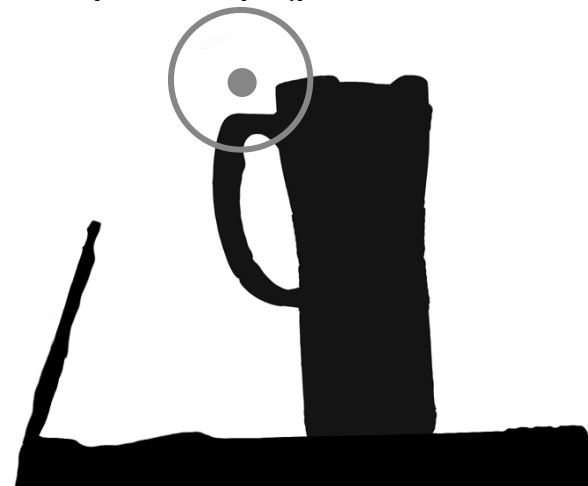


Photoshop lens blur

- **Reverse-engineered algorithm: average over circle**
- **Size of circle depends on pseudo depth**
- **Discard pixels that are too much closer**



Depth map (painted manually)



Photoshop lens blur

- **Filter>Blur>Lens blur**



Depth map (painted manually)

